LOG(F): AN OPTIMAL COMBINATION OF LOGIC PROGRAMMING, REWRITING,
AND LAZY EVALUATION

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April 1988

P-7437

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ABSTRACT

A new approach for combining logic programming, rewriting, and lazy evaluation is described. It rests upon *subsuming* within logic programming, instead of upon *extending* it with, rewriting, and lazy evaluation.

A non-terminating, non-deterministic rewrite rule system, F* and a reduction strategy for it, select, are defined. F* is shown to be reduction-complete in that select simplifies terms whenever possible. A class of F* programs called Deterministic F* is defined and shown to satisfy confluence, directedness, and minimality. Confluence ensures that every term can be simplified in at most one way. Directedness eliminates searching in simplification of terms. Minimality ensures that select simplifies terms in a minimum number of steps. Completeness and minimality enable select to exhibit, respectively, weak and strong forms of laziness.

F* can be compiled into Horn clauses in such a way that when SLD-resolution interprets these, it directly simulates the behavior of select. Thus, SLD-resolution is made to exhibit laziness. LOG(F) is defined to be a logic programming system augmented with an F* compiler, and the equality axiom X=X. LOG(F) can be used to do lazy functional programming in logic, implement useful cases of the rule of substitution of equals for equals, and obtain a new proof of confluence for combinatory logic. (RW)

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I. INTRODUCTION

I.1 THE PROBLEM

Logic programming [Kowalski 1979], is the use of statements of logic as computer programs. It has led to new insights into computing as well as logic. Rewriting is synonymous with reduction, as described, for example, in [Knuth & Bendix 1970]. It is simplification of an expression by successive application of some collection of rewrite rules. Its usefulness is evident from its appearance in many branches of mathematics. Lazy evaluation, e.g. [Vuillemin 1974], is a method of computing which ensures that a computation step is performed only when there is need to perform it. Thus, not only does it enable certain computations to terminate more quickly, it also enables computation with infinite data structures.

A system in which logic programming, rewriting, and lazy evaluation were combined could put considerable programming power at our disposal. In particular, it would simultaneously afford the expressive power of both functions, and relations.

Furthermore, such a system could be used to implement instances of the rule of substitution of equals for equals in logical statements. This is a very important rule, as witness its use in the simplest of mathematical derivations, e.g. solution of trigonometric identities. Logical statements could be expressed using logic programs, while equality theories could be expressed using rewrite rules.

We propose a new approach for building the above system which is rigorous, as well as computationally efficient. It rests upon *subsuming* within logic programming, instead of *extending* it with, rewriting and lazy evaluation. This means that SLD-resolution, the proof procedure used for logic programming, is not changed. Instead, Horn clauses, or *pure* Prolog clauses are written in such a way, that when SLD-resolution interprets them, it directly simulates lazy rewriting. The resulting system is called LOG(F). It can be said to make contributions to the following three areas:

> **1. Rewriting.** Simple, syntactic conditions are defined under which non-terminating, non-deterministic rewrite rules, with pattern matching, satisfy useful computational properties. These are regarding demand-driven reduction, confluence, elimination of search during reduction, and lengths of reductions.

> **2. Combination of logic programming and rewriting.** It is shown how rewriting can be *subsumed* within logic programming. In particular, the above computational properties of rewriting are realized within logic programming, without changing it, and without sacrificing logical rigor. This has two important

consequences.

First, a satisfactory combination of logic programming, and rewriting is achieved, *without* developing a new computational model of which the two are instances. Developing such a model is quite difficult, particularly if it is to have satisfactory declarative, *and* satisfactory procedural semantics. Second, full advantage is taken of the very efficient implementations of Prologs. Thus, formidable problems that implementation of the new model would very likely pose, are avoided.

3. Lazy evaluation. By 1 and 2, it is shown how lazy evaluation can be done *efficiently, within* the normally eager framework of logic programming. Thus a basis is established for understanding lazy evaluation purely in terms of well understood ideas in first order logic. Also, a new, and powerful use is found for an old, and widely used tool, namely, Prolog.

I.2 SUMMARY OF MAIN RESULTS

I.2.1 A rewrite rule system F*

A first-order rewrite rule system F*, with pattern matching, is defined. The function symbols are partitioned *in advance* into constructors, and non-constructors. Simplification in F* means reducing ground terms to simplified forms i.e. terms of the form $c(t1,..,tn)$ where c is a constructor symbol, and each of $t1,..,tn$ is a ground term. Simplified forms can be used to represent finite approximations to infinite structures, and are analogous to head-normal forms in the lambda-calculus [Wadsworth 1976]. In contrast, a normal form is defined to be a term in which all function symbols are constructors.

Now, an important point is that a method for computing simplified forms can be used repeatedly to compute normal forms. Moreover, it would terminate more often than would a method which directly computes normal forms. Hence it is sufficient to develop, and study properties of, a method for computing simplified forms.

An F* program is a finite set of rules, each of the form LHS=>RHS, satisfying the following restrictions: (1) LHS is of the form $f(L1,..,Lm)$, m>=0, f a non-constructor function symbol, and each Li either a variable, or of the form $c(T1,..,Tn)$, n>=0, c a constructor symbol, and each Ti a variable, (2) a variable occurs at most once in LHS, and (3) all variables of RHS occur in LHS. Note that *non-terminating, non-deterministic* sets of rewrite rules are permissible. Also any rule with left hand side of depth greater than two can easily be expressed in terms of rules with left hand sides of depth at most

two, as required by (1).

Where P is an F* program, and f(T1,..,Tn) a ground term, a reduction strategy for P, $select_p$, is defined by the following pseudo-Horn clauses:

> $select_p$(f(T1,..,Tn),f(T1,..,Tn)) if f(T1,..,Tn)=>$_p$X.
> $select_p$(f(T1,..,Ti,..,Tn),X) if
>> there is a rule f(L1,..,Li,..,Ln)=>RHS in P, and
>> there is no substitution σ such that Ti=Liσ, and
>> $select_p$(Ti,X).

Here A=>B means there is a rule LHS=>RHS such that A matches LHS with substitution σ, and B is RHSσ. Select is shown to be *reduction-complete*, in that if a term can be simplified, it can be simplified by reducing it via select. *Thus select exhibits a weak form of laziness.* An example of an F* program is:

> perm([])=>[].
> perm([AIV])=>insert(U,perm(V)).
> insert(U,X)=>[UIX].
> insert(U,[AIB])=>[Alinsert(U,B)].

Here [], I are constructors, while perm, insert are non-constructors. The term perm([1,2,3]) is now reduced by select to [1Iperm([2,3])], [2Iinsert(1,perm([3]))], and [3Iinsert(1,insert(2,perm([])))]. If further reduction is desired, select may be called recursively upon the arguments of I to yield each of [1,2,3], [1,3,2], [2,3,1], [2,1,3], [3,1,2], [3,2,1].

I.2.2 Deterministic F*

An F* program P is a DF* program if (1) left hand sides of no two rules in P unify, and (2) where f(L1,..,Li,..,Lm)=>RHS is a rule in P, and Li is not a variable, then in every other rule f(K1,..,Ki,..,Km)=>RHS1 in P, Ki is not a variable. These restrictions are very reasonable. and as examples throughout this paper show, it is possible to adhere to these, yet write quite expressive programs.

DF* is shown to satisfy *confluence, directedness*, and *minimality*. Confluence ensures that a term can be simplified in at most one way. Directedness ensures that to simplify a term it is sufficient to compute *any* reduction computable by select. Moreover, all reductions computable by select are of equal length. Thus, during reduction, no searching is necessary. Provided, whenever a term is reduced, all copies of it are simultaneously reduced, minimality ensures that select simplifies terms in a minimum

number of steps. *Thus, select exhibits a strong form of laziness.* An example of a DF*
program is:

```
append([],X)=>X.
append([U|V],W)=>[U|append(V,W)].
interleave([U|V],X)=>[U|interleave(X,V)].
a=>[1|a].
b=>[2|b].
```

However, the F* program above to insert an element non-deterministically into a list is
not in DF*.

I.2.3 Compiling F* into Horn clauses

F* programs can be compiled into Horn clauses in such a way that when SLD-resolution
interprets these, it directly simulates the behavior of (the interpreter based upon) select.
This means that there is, essentially, a one-to-one correspondence between steps executed
by (the interpreter based upon) select, and steps executed by SLD-resolution. This is
accomplished by translating each F* rule into a distinct Horn clause, and *simultaneously*
embodying in that clause, information about the logic of the rule, as well as information
about the control of select when interpreting that rule.

Thus, SLD-resolution is made to exhibit laziness. If the F* program is also in DF*,
clauses can be further transformed to eliminate all backtracking. Finally, clauses can be
compiled into machine code by Prolog compilers. The compilation algorithm consists of
two steps:

Step 1. For each n-ary, n>=0, constructor symbol c in P, and where X1,..,Xn are distinct
variables, generate the clause:

```
reduce(c(X1,..,Xn),c(X1,..,Xn))
```

Step 2. Let f(L1,..,Lm)=>RHS be a rule in P. Let A1,..,Am,Out be distinct Prolog
variables not occurring in the rule. If Li is a variable let Qi be Ai=Li. If Li is c(X1,..,Xn)
where c is a constructor symbol, and each Xi a variable, let Qi be reduce(Ai,c(X1,..,Xn)).
Generate the clause:

```
reduce(f(A1,..,Am),Out):-Q1,..,Qm,reduce(RHS,Out).
```

In practice, if Li is a variable, Qi can be dropped, provided Ai is replaced by Li in
f(A1,..,Am). For example, the above F*, and DF* programs are compiled into:

```
reduce([],[]).
reduce([UIV],[UIV]).

reduce(perm(X),Z):-reduce(X,[]),reduce([],Z).
reduce(perm(X),Z):-reduce(X,[FXIRX]),reduce(insert(FX,perm(RX)),Z).
reduce(insert(A,X),Z):-reduce([AIX],Z).
reduce(insert(A,X),Z):-reduce(X,[FXIRX]),reduce([FXIinsert(A,RX)],Z).
reduce(append(X,Y),Z):-reduce(X,[]),reduce(Y,Z).
reduce(append(X,Y),Z):-reduce(X,[UIV]),reduce([UIappend(V,Y)],Z).
reduce(interleave(X,Y),Z):-reduce(X,[UIV]),reduce([UIinterleave(Y,V)],Z).
reduce(a,Z):-reduce([1Ia],Z).
reduce(b,Z):-reduce([2Ib],Z).
```

If we now type, in Prolog, reduce(perm([1,2,3]),Z), we obtain Z=[1Iperm([2,3])], Z=[2Iinsert(1,perm([3]))], and Z=[3Iinsert(1,insert(2,perm([])))]. Note the following: First, perm([1,2,3]) is only partially reduced, and *directly* by Prolog, not by some lazy interpreter implemented in Prolog. Second, the terms to which Z is bound are exactly those to which perm([1,2,3]) is reduced by select. This illustrates Prolog simulating behavior of select. If we now define:

```
first(0,X,[]).
first(N,X,[FXIZ]):-not(N=0),reduce(X,[FXIRX]),N1 is N-1,first(N1,RX,Z).
make_list(E,[]):-reduce(E,[]).
make_list(E,[FEIZ]):-reduce(E,[FEIRE]),make_list(RE,Z).
print_list(X):-reduce(X,[FXIRX]),write(FX),write(','),print_list(RX).
```

and then type, make_list(perm([1,2,3]),Z), we obtain Z=[1,2,3], Z=[1,3,2], Z=[2,1,3], Z=[2,3,1], Z=[3,1,2], Z=[3,2,1]. As further examples, if we type the queries on the left-hand side, we obtain the answers on the right-hand side:

```
reduce(append(a,b),Z) ---> Z=[1Iappend(a,b)]
reduce(interleave(a,b),Z) ---> Z=[1Iinterleave(b,a)]
first(5,interleave(a,b),Z) ---> Z=[1,2,1,2,1]
print_list(interleave(a,b)) ---> 1,2,1,2,1,2,.....
```

I.2.4 LOG(F)

LOG(F) is defined to be a logic programming system augmented with an F* compiler, and the equality axiom X=X. The result of compilation is to add to a logic programming system, a primitive for lazily simplifying F* terms. This primitive can be called from other Horn clauses, so LOG(F) is proposed as a combination of logic programming,

rewriting and lazy evaluation.

For problems for which lazy evaluation does not reduce lengths of computation, e.g. sorting, or all permutations, LOG(F) is empirically found to be about five times slower than Prolog. For problems for which lazy evaluation does reduce lengths of computation, e.g. N-queens, LOG(F) is faster than Prolog by unbounded, even infinite, amounts.

In the literature, [Vuillemin 1974, Berry & Levy 1979], optimality is used synonymously with minimality. Due to minimality of DF*, LOG(F) can also be said to be optimal. It can also be said to be so in a weaker sense, because of its desirable computational properties, and their economical realization in Prolog.

I.2.5 Applications of LOG(F)

LOG(F) can be used to do lazy functional programming in logic. In particular, it can be used to manipulate representations of infinite structures, such as in real analysis, exact real arithmetic, graphics, or networks of communicating processes.

The SKI rules of combinatory logic can be expressed as a DF* program. From confluence of DF*, a new proof is obtained of the confluence of combinatory logic.

DF* seems to offer a reasonable compromise between sequential execution and unbounded parallelism. Due to directedness of DF*, arguments of f in f(t1,...,tm) can be simplified in parallel, however, they would be simplified lazily. Thus, DF* seems to be a good candidate for implementation on parallel machines.

Finally, if a DF* program is interpreted as an equality theory, reduce clauses can be thought of as implementing an equality theory in Prolog with the restriction that it be used only for simplification of terms. Now, given a clause of the form p(c(X1,..,Xm)):-Body, where c is a constructor symbol, we can add another clause stating a rule of substitution of equals:

$$p(X):-reduce(X,c(X1,..,Xm)),p(c(X1,..,Xm)).$$

Now, even when a term E is not of the form c(X1,..,Xm), p can still be inferred for E, provided E is reducible to a term of the form c(X1,..,Xm). For example, with the Prolog rule for computing perimeters of regular polygons, peri(reg_poly(N,S),Z):-Z is N*S, we can infer peri(reg_poly(3,10),30). We can now add the clause:

$$peri(X,Y):-reduce(X,Z),peri(Z,Y).$$

Where reg_poly is a constructor, and equi, square, and hexagon are non-constructors, an equality theory among polygons, expressed in F*, is:

```
equi(S)=>reg_poly(3,S).
square(S)=>reg_poly(4,S).
hexagon(S)=>reg_poly(6,S).
```

This is compiled into:

```
reduce(reg_poly(A,B),reg_poly(A,B)).
reduce(equi(S),Z):-reduce(reg_poly(3,S),Z).
reduce(square(S),Z):-reduce(reg_poly(4,S),Z).
reduce(hexagon(S),Z):-reduce(reg_poly(6,S),Z).
```

The Prolog query peri(equi(10),30), now succeeds. Thus Prolog automatically infers the result of substituting equi(10) for reg_poly(3,10), in peri(reg_poly(3,10),30). Of course, if we type peri(square(3),Z), we obtain Z=12.

I.3 RELATIONSHIP WITH PREVIOUS WORK

There seem to be two major approaches to combining logic programming, and rewriting. The first consists of implementing logic programming in rewriting, e.g. LOGLISP [Robinson & Sibert 1982], or QLOG [Komorowski 1982]. However, it seems difficult for such an approach to lead to an efficient system since logic programs must pass through two high-level layers of interpretation.

The second approach consists of developing a new computational model of which both rewriting, and logic programming are instances. Examples of such models include those based upon upon semantic- or T-unification, [Goguen & Meseguer 1986], [Subrahmanyam & You 1984], [Kornfeld 1983], sets, [Robinson 1987], [Darlington et al. 1986], narrowing, [Reddy 1985], the Knuth-Bendix completion procedure, [Dershowitz & Josephson 1984], oriented equational clauses, [Fribourg 1984], residuation, [Ait-Kaci & Nasr 1987], extension of SLD-resolution with narrowing, [Yamamoto 1987], or extension of SLD-resolution with atom-elimination rule, [Barbuti et al. 1986].

In order for a new computational model to be satisfactory, it must posssess not only good declarative semantics, but also good procedural semantics. The former is essential for reasoning about programs in the model. The latter means that the behavior of the model is simple enough that it can be visualized, predicted, and controlled. It is essential if the model is to be used for programming, i.e. for expressing algorithms. In this regard, we also quote Robinson [1984]:

...one guiding principle must surely be that logic programming, however narrowly or broadly construed, essentially involves the ingredient of practicality. The underlying deductive processes should have enough directness and predictability to permit the planning of efficient logical computations. Herein probably lies the important distinction, difficult to make precise but nonetheless real, between logic programming proper and automatic deduction in general.

However, developing a satisfactory computational model, more general than logic programming and rewriting, is a very ambitious undertaking, particularly if the model is also to exhibit laziness. In particular, it appears that each of the above models, with the possible exception of [Robinson 1987], and [Darlington et al. 1986], either has complex declarative semantics, or complex procedural semantics.

Of course, even if a satisfactory computational model is developed, its efficient implementation on concrete machines can still pose a considerable software engineering challenge, requiring several person-years of effort. In particular, it appears that efficient implementation of the above proposals is still an ongoing effort.

Lazy evaluation itself does not seem to be easy to implement efficiently. Several implementations of lazy evaluation for functional, and logic-based languages have been proposed e.g. [Friedman & Wise 1976, Henderson 1980, Turner 1979, O'Donnell 1985, Clark & McCabe 1979, Hansson et al. 1982, Shapiro 1983, Barbuti et al. 1986]. However, only a few of these systems, e.g. Turner's, or O'Donnell's, seem to be efficient enough for practical programming.

In view of such difficulties with developing, and implementing a new computational model of which logic programming, rewriting, and lazy evaluation, are instances, we ask whether it is possible to *subsume* the last two within the first. In other words, we ask whether it is possible to keep SLD-resolution fixed, but use it in such a way that it performs, *in a computationally feasible manner*, rewriting, and lazy evaluation? If such an attempt were to succeed, we would not only obtain a declarative semantics of rewriting, and lazy evaluation using purely logical ideas, we would also have a very efficient implementation of these, in, say, Prolog.

Important precedents in this direction have already been established with the subsumption, within logic programming, of grammars, and relational databases. Definite clause grammar rules [Pereira & Warren 1980] can be expressed as Horn clauses in such a way that their interpretation using Prolog, directly simulates top-down parsing. Relational databases can be expressed directly as ground Horn clauses [Gallaire & Minker 1978]. Prolog enables inference with them in ways (e.g. using recursion) not possible with conventional data retrieval operators.

An important step towards subsuming rewriting within logic programming, has recently been taken by van Emden & Yukawa [1987], whose motivations are very similar to, but independent, of ours. They show how to derive logical consequences of the standard equality axioms which result in a small SLD-search space. They also show how to compile an equality theory into equality free Horn clauses, which also result in a small SLD-search space. *However, their approach is restricted only to terminating equality theories.* These are insufficient for representing infinite structures.

As pointed out in [Narain 1986], the compactness theorem of first order logic [Robinson 1979] suggests that lazy evaluation is already present in first order logic. It states that if an infinite set of clauses is unsatisfiable then it has a finite subset which is also unsatisfiable. Moreover, a complete proof procedure, such as SLD-resolution for Horn clauses would find this set in finite time. Thus, as with lazy evaluation, one could get termination in finite time even with an infinite input.

This idea was investigated further, and led to a method in [Narain 1986], for defining functions by Horn clauses in such a way that when SLD-resolution interprets these, it behaves lazily. However, the discussion is limited mainly to lists, although a generalization to other data structures is hinted.

The current system, LOG(F), is an attempt to generalize, and develop a purely syntactic explanation of the above method. It appears to subsume within logic programming, in a rigorous yet computationally efficient fashion, non-terminating, non-deterministic rewriting, and lazy evaluation.

Minimality of DF* appears to be a generalization of similar results by Vuillemin [1974], and Berry & Levy [1979]. Both derive it only for rewrite rules whose left hand sides are of the form f(X1,..,Xm), where each Xi is a variable. Thus, they must assume existence of a finite number of primitive functions such as if-then-else, which are not definable using such rules alone. In contrast, F* admits rewrite rules in which the Xi can be patterns. Thus, in F*, as in logic programming, it is not necessary to assume existence of any primitive functions.

Restrictions on rewrite rules in F*, and the reduction strategy select, seem to be substantially simpler than their counterparts in the system of O'Donnell [1985]. Select also seems to be substantially simpler than its counterpart in the system of Huet & Levy [1979]. Furthermore, since F* can be compiled into efficient Horn clauses, and Prolog can be used, implementation of F* is straightforward. However, implementation of the other two systems seems to be quite a major undertaking.

Confluence of DF* is anticipated by Huet [1980] who derives sufficient conditions for

confluence for rewrite rule systems more general than DF*. However, our proof, being specialized for DF*, is very simple.

LOG(F) bears only a superficial similarity to the system of Tamaki [1984]. He also shows how to compile equality theories into Horn clauses with a smaller search space. However, as is pointed out in his paper, these clauses can still be seriously inefficient, particularly, when manipulating representations of infinite structures. As shown in Section VI.8, such inefficiency is not exhibited by LOG(F). Also, his reducibility predicate can terminate even without simplifying terms whereas that of LOG(F) cannot.

I.4 OUTLINE OF PAPER

Section II defines F*, and the reduction strategy select, and establishes its reduction-completeness. Section III defines DF*, and shows its confluence and directedness. Section IV defines Labeled DF*, a subset of DF*, for the purpose of formalizing the notion of a copy of a term, and then establishes its minimality. Section V describes an algorithm for compiling F* into Horn clauses, and proves its correctness. Section VI describes examples of programming in LOG(F), and compares performance of LOG(F) with that of Prolog. Section VII contains a summary and conclusions. Proofs of relatively minor propositions have been omitted, or abbreviated. These can be obtained in full in [Narain 1988].

II. A REWRITE RULE SYSTEM F*

II.1 INTRODUCTION

A first order, non-deterministic, non-terminating rewrite rule system F*, and a lazy reduction strategy for it, select, are defined. The emphasis in F* is on computing simplified forms, instead of normal forms. Thus, termination problems faced by certain previous approaches are avoided.

The main result proved is that F* is reduction-complete, in that select reduces ground terms to their simplified, or normal forms, whenever possible. Reduction-completeness yields a weak form of laziness. A term may denote an infinite object, and so fail to have a finite normal form. However, if it has a finite simplified form, it is obtained in finite time. By repeatedly simplifying subterms of this simplified form, the structure of the infinite object can be revealed to any arbitrary depth.

II.2 DEFINITION OF F*

Variables. There is a countably infinite list of variables.

Function symbols. There is a countably infinite list of 0-ary function symbols. In particular, [], 0, true, false, are 0-ary function symbols. There is a countably infinite list of 1-ary function symbols. In particular, s is a 1-ary function symbol. There is a countably infinite list of 2-ary function symbols. In particular, I is a 2-ary function symbol. And so on, for all other arities.

Connectives. The connectives are =>, (,), ',',.

Constructor Symbols. There is an infinite subset of the function symbols called Constructors. Each element of Constructors is called a constructor symbol. For each n, n>=0, Constructors contains an infinite number of n-ary function symbols. In particular, 0, true, false, [] and I are constructor symbols. It is intended that data be represented by combinations of only constructor symbols.

Terms. A term is either a variable, or an expression of the form f(t1,..tn) where f is an n-ary function symbol, n>=0, and each ti is a term. A term is called ground if it contains no variables. *It is the intention in F* to reduce only ground terms,* and most of the propositions below are about these. Non-ground terms such as left hand sides of reduction rules do arise, but in very few propositions. **Hence, unless explicitly stated otherwise, by a term is meant a ground term.**

Subterms. Let E be a term. Then E is said to be a subterm of itself. Also, if E=f(t1,..,tn), n>0, then X is said to be a subterm of E, if X is a subterm of some ti. Let X be a subterm of E. Then X is said to occur in E. Also, if X≠E, then X is said to be a proper subterm of E, or be properly contained in E. Two subterms A and B of E are said to overlap, if A is properly contained within B.

Substitutions. A substitution is a, possibly empty, set {<X1,t1>,..,<Xn,tn>} where the X1,..,Xn are distinct variables, and each ti is a term, possibly containing variables. A variable X is defined in a substitution σ iff for some possibly non-ground term s, <X,s> occurs in σ. In this paper, we will be concerned almost exclusively with substitutions in which for each pair <X,s>, s is a ground term.

Applying substitutions to terms. Let σ={<X1,t1>,..,<Xn,tn>} be a substitution and E be a term, possibly containing variables. The result of applying σ to E, Eσ, is the result of replacing, for each i, every occurrence of Xi in E by ti.

Matching. A ground term E is said to **match** a possibly non-ground term F, with substitution α, if E=Fα.

Unification. Two terms, E and F, possibly containing variables, are said to unify with substitution σ if Eσ=Fσ. Note that matching is a special case of unification.

Reduction Rules. A reduction rule is of the form:

LHS=>RHS

where LHS and RHS are terms, possibly containing variables. LHS is called the head of the rule. The following restrictions are placed on LHS and RHS:

(a) LHS is not a variable.

(b) LHS is not of the form c(t1,..,tn) where c is a constructor symbol.

(c) If LHS=f(t1,t2,..,tn), then each ti is a variable, or a term of the form c(X1,..,Xm) where c is an m-ary constructor symbol, and each Xi a variable.

(d) There is at most one occurrence of any variable in LHS.

(e) All variables of RHS appear in LHS.

These restrictions are very reasonable, and as examples throughout the paper show, very

expressive programs can be written adhering to these. *Note that F* is more expressive than first order Lisp, as the latter does not admit patterns in left hand sides of function definitions.*

Restriction (a) is to enable functional programs to be written in F*.

Restriction (b) ensures that a term of the form c(t1,..,tn), c a constructor symbol, cannot be reduced as a whole. This yields a simple halting condition for the basic simplification process. If further simplification is required, the process may be called recursively.

Restriction (c) limits heads of rules to be of depth at most two, and so greatly simplifies analysis. However, no generality is lost, since rules with heads of arbitrary depth can easily be expressed in terms of rules with heads of depth at most two. For example, the rule:

```
fib(s(s(X)))=>plus(fib(X),fib(s(X)))
```

can be expressed as:

```
fib(s(A))=>g(A)
g(s(X))=>plus(fib(X),fib(s(X))).
```

Restriction (d) is the linearity assumption. It ensures that to match a ground term f(t1,..,tn) with the left hand side of a rule f(L1,..,Ln), it is sufficient to match, for each i, ti with Li.

Restriction (e) ensures that a ground term is never reduced to a non-ground term. Again, this is necessary if F* is to be used for functional programming.

F* programs. An F* program is a finite set of reduction rules. Where t is a binary constructor symbol, some examples of F* programs are:

```
quicksort([])=>[].
quicksort([A|B])=>quicksort1(A,partition(A,B,[],[])).
quicksort1(A,t(L,R))=>append(quicksort(L),[A|quicksort(R)]).

partition(U,[],L,R)=>t(L,R).
partition(U,[A|B],L,R)=>
        if(lesseq(A,U),partition(U,B,[A|L],R),partition(U,B,L,[A|R])).

append([],X)=>X
```

append([U|V],W)=>[U|append(V,W)]

if(true,X,Y)=>X.
if(false,X,Y)=>Y.

lesseq(0,X)=>true.
lesseq(s(X),s(Y))=>lesseq(X,Y).
lesseq(s(X),0)=>false.

zero(X)=>0.
prim_rec_f(0,Y1,Y2,Y3)=>g(Y1,Y2,Y3).
prim_rec_f(s(X),Y1,Y2,Y3)=>h(prim_rec_f(X,Y1,Y2,Y3),X,Y1,Y2,Y3).
minim_p(X,K)=>if(equal(p(X),K),X,minim_p(s(X),K)).

equal(0,0)=>true.
equal(0,s(X))=>false.
equal(s(X),0)=>false.
equal(s(X),s(Y))=>equal(X,Y).

merge([A|B],[C|D])=>if(lesseq(A,C),[A|merge(B,[C|D])],[C|merge([A|B],D)]).

int(N)=>[N|int(s(N))].

greater(X,Y)=>not(lesseq(X,Y)).

not(true)=>false.
not(false)=>true.

We now consider the reduction of **terms**. Again, unless explicitly stated, by a term we mean a ground term.

$E=>_P E1$. Let P be an F* program and E and E1 be terms. We say $E=>_P E1$ if there is a rule LHS=>RHS in P, and a substitution σ such that E=LHSσ, and E1=RHSσ. We also say that E reduces to E1 by the rule LHS=>RHS, or that the rule applies to the whole of E. The subscript on => is dropped, if clear from context.

F=E[G/H]. Where E,F,G,H, are terms, let F be the result of replacing an occurrence of G in E by H. Then we say F=E[G/H].

$E->_P E1, E-^*>_P E1$. Let P be an F* program and E be a term. Let G be a subterm of E such that $G=>_P H$. Let E1 be the result of substituting H for G in E. Then we say that E-

$>_pE1$. Note that if $E=>_pE1$ then E matches the left hand side of some rule in P. If $E->_pE1$ then some subterm of E, including possibly E, matches the left hand side of some rule in P. We define $-*>_p$ to be the reflexive transitive closure of $->_p$. Again, the subscript on $->$ or $-*>$ is dropped, if clear from context.

Reductions. Let P be an F* program. A reduction in P is a, possibly infinite, sequence $E1,E2,...$ such that for each i, when Ei and Ei+1 both exist, $Ei->_pEi+1$.

Lengths of reductions. The length of a finite reduction $E0,E1,..,En$ is n.

Simplified forms. A term is said to be in simplified form or simplified if it is of the form $c(t1,..,tn)$ where c is an n-ary constructor symbol, $n>=0$, and each ti is a term. F is called a simplified form of E, if $E-*>F$ and F is in simplified form.

Normal forms. A term is said to be in normal form if each function symbol in it is a constructor symbol. F is called a normal form of E if $E-*>F$ and F is in normal form.

Successful reductions. Let P be an F* program. A successful reduction in P is a finite reduction $E0,..,En$, $n>=0$, in P, such that En is simplified.

$R_p(G,H,A,B)$. Let P be an F* program. Where G,H,A,B are terms, $R_p(G,H,A,B)$ if (a) $G=>H$, and (b) B is identical with A except that zero or more occurrences of G in A are *simultaneously* replaced by H. Note that A and G can be identical. Again, if P is clear from context we omit the subscript on R.

Reduction strategy. Let P be an F* program. A reduction strategy for P takes as input a term E and selects a subterm G of E such that there exists a term H such that $G=>_pH$.

A special reduction strategy. Let P be an F* program. We now define a reduction strategy, $select_p$ for P. Informally, given a term E it will select that subterm of E whose reduction is necessary in order that some $=>$ rule in P apply to the whole of E. Where $f(T1,..,Tn)$ is a term, the relation $select_p$ is defined by the following pseudo-Horn clauses:

> $select_p(f(T1,...,Tn),f(T1,...,Tn))$ if $f(T1,...,Tn)=>_pX$.
> $select_p(f(T1,...,Ti,...,Tn),X)$ if
> >   there is a rule $f(L1,..,Li,..,Ln)=>RHS$ in P, and
> >   there is no substitution σ such that $Ti=Li\sigma$, and
> > $select_p(Ti,X)$.

The second rule is a schema, so that an instance of it is assumed written for each each i, $1=<i=<n$. Again, the subscript on select is dropped, if clear from context. Note the

following:

(1) When $select_p$ takes as input E and returns G, it also, implicitly, computes a position, or occurrence of G in E. This occurrence can be obtained from the proof of $select_p(E,G)$.

(2) If $select_p(E,G)$, there is a term H such that $G =>_p H$.

(3) Select is non-deterministic, in that given term E, it is possible for it to select more than one subterm A1,..,Ak, k>0, within E. Also, it is possible that for some i,j, i≠j, Ai is a proper subterm of Aj.

(4) Since, by restriction (b) there is no rule in P of the form c(t1,..,tn)=>RHS, where c is a constructor symbol, if E is simplified, $select_p$ is undefined for E.

For example, where P is the set of reduction rules which appear above, and 1,2,... are abbreviations, respectively, for s(0),s(s(0)),.., we have the following:

    select(merge(int(1),int(2)),int(1)).
    select(merge(int(1),int(2)),int(2)).
    select(merge([1,3],int(2)),int(2)).
    select(merge([1,2],[3,4]),merge([1,2],[3,4])).
    If E=[1|merge(int(1),int(2))] then select is undefined for E.
    select(lesseq(0,zero(1)),lesseq(0,zero(1))).
    select(lesseq(0,zero(1)),zero(1)).

Let E,G,H be terms. In the following, when we say that select(E,G), and G is to be replaced by H in E, we mean that the occurrence of G derived from the proof of select(E,G), is to be replaced by H.

N-step. Let P be an F* program and E,G,H be terms. Let $select_p(E,G)$, and $G =>_p H$. Let E1 be the result of replacing G by H in E. Then we say that E reduces to E1 in an N-step in P. The qualification "in P" is omitted when P is clear from context. The prefix N in N-step is intended to connote normal order.

N-reduction. Let P be an F* program. An N-reduction in P is a reduction E1,E2,.... in P such that for each i, when Ei and Ei+1 both exist, Ei reduces to Ei+1 in an N-step in P. In particular, the sequence E where E is a term, is an N-reduction in P. The qualification "in P" is omitted when P is clear from the context.

select-r. This reduction strategy repeatedly uses select to reduce terms. The suffix r

stands for recursive, or repeated. Where P is an F* program:

> select-r$_p$(E,F) if select$_p$(E,F).
> select-r$_p$(c(T1,..,Ti,..,Tm),F) if
> > c is a constructor symbol, and
> > select-r$_p$(Ti,F).

Again, the second rule is a schema, so that an instance of it is assumed written for each i, 1=<i=<n. Thus, select-r is like select except that if a term is in simplified form, it recursively uses select on one of the arguments of the outermost constructor symbol. So, its repeated use can yield normal-forms of terms.

For example, with the usual rules for append, the query select([1|append([],[])],X) fails, whereas the query select-r([1|append([],[])],X) succeeds with X=append([],[]). The subscript on select-r is dropped, if clear from context.

NR-step. Let P be an F* program and E,G,H be terms. Suppose select-r$_p$(E,G) and G=>$_p$H. Let E1 be the result of replacing G by H in E. Then we say that E reduces to E1 in an NR-step in P. The qualification "in P" is omitted when clear from context.

NR-reduction. Let P be an F* program. An NR-reduction in P is a reduction E1,E2,.... in P such that for each i, when Ei and Ei+1 both exist, Ei reduces to Ei+1 in an NR-step in P. In particular, the sequence E where E is a term, is an NR-reduction in P.

NR-reductions are needed to compute normal-forms of terms. For example, the term append([1],[2]) has the only N-reduction append([1],[2]), [1|append([],[2])]. However, it has the NR-reduction append([1],[2]), [1|append([],[2])], [1,2]. The qualification "in P" is omitted when clear from context.

II.3 REDUCTION-COMPLETENESS OF F*

Lemma 1. Let P be an F* program. If A->B and B is simplified but A is not, then A=>B.

Proof. Clear, from restriction (b). **QED.**

Lemma 2. Let P be an F* program. Let X1,..,Xn be variables, G,H,t1,..,tn,t1*,..,tn* be terms such that for each i, R(G,H,ti,ti*). Let σ={<X1,t1>,..,<Xn,tn>} and τ={<X1,t1*>,..,<Xn,tn*>} be substitutions. Let M be a term, possibly containing variables, but only from {X1,..,Xn}. Then R(G,H,Mσ,Mτ).

Proof. By induction on length of M. **QED.**

Lemma 3. Let P be an F* program. If:

> (1) G, H, E1=f(t1,..,tn) and F1=f(t1*,..,tn*) are terms, and
> (2) R(G,H,ti,ti*) for every i in 1,..,n, and
> (3) B=f(L1,..,Ln) is the head of some rule in P, and
> (4) E1=Bσ for some substitution σ, which defines only the variables in B.

Then there exists a substitution τ such that:

> (1) F1=Bτ, and
> (2) σ and τ define exactly the same variables, and
> (3) If pair <X,s> occurs in σ, and <X,s*> occurs in τ, then R(G,H,s,s*).

Proof. Clear, by restrictions (a)-(e). **QED.**

Lemma 4. Let P be an F* program. If:

> (1) f(t1,..,ti,..,tn) is a term, and
> (2) f(L1,..,Li-1,c(X1,..,Xm),Li+1,..,Ln)=>RHS is a rule in P, and
> (3) ti=d1,d2,d3,..,dr, r>0, is an N-reduction.

Then, f(t1,..,ti-1,d1,ti+1,..,tn), f(t1,..,ti-1,d2,ti+1,..,tn), .., f(t1,..,ti-1,dr,ti+1,..,tn) is also an N-reduction.

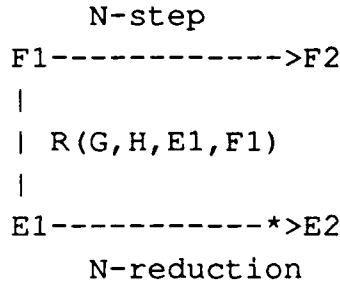**Proof.** By definition of N-reduction. **QED.**

Theorem 1. Let P be an F* program. Let E1,F1,F2,G,H be terms such that

> (1) R(G,H,E1,F1), and
> (2) F1 reduces to F2 in an N-step

Then there is an N-reduction E1,..,E2 in P such that R(G,H,E2,F2).

Proof. It is helpful to draw the following diagram:

```
      N-step
F1----------->F2
|
| R(G,H,E1,F1)
|
E1----------*>E2
      N-reduction
```

We have to show that R(G,H,E2,F2). We proceed by induction on length of E1. Suppose E1 is a 0-ary function symbol. If E1=F1 then E1,F2 is an N-reduction and R(G,H,F2,F2). If E1≠F1 then since R(G,H,E1,F1), E1=G and E1=>F1. Thus, there is an N-reduction E1,F1,F2 and R(G,H,F2,F2). In both cases, take E2=F2.

Otherwise, E1=f(t1,..,tn), n>0. Assume the theorem for every term whose length is less than that of f(t1,..,tn). If E1=F1 then E1,F2 is an N-reduction and R(G,H,F2,F2). Otherwise E1≠F1. If E1=G then since R(G,H,E1,F1), E1=>F1. Thus, there is an N-reduction E1,F1,F2, and R(G,H,F2,F2). Again, in both cases, take E2=F2.

We now arrive at the interesting cases, with E1≠F1, but G≠E1. Hence F1=f(t1*,..,tn*) where for every i, R(G,H,ti,ti*). We now consider the following cases:

Case 1. F1=>F2. Then there is a rule f(L1,..,Ln)=>RHS in P, such that F1 matches f(L1,..,Ln) with substitition τ, and F2=RHSτ.

> **Case 1-1.** E1 matches f(L1,..,Ln) with substitution σ. By Lemma 3, there exists substitution β such that F1=f(L1,..,Ln)β. Since F1=f(L1,..,Ln)τ, τ=β.
>
> E1=>RHSσ, so let E2=RHSσ. The N-reduction is E1,E2. Of course F2=RHSτ. By Lemma 3, σ and τ define exactly the same variables, and if <X,s> occurs in σ and <X,s*> appears in τ then R(G,H,s,s*). Hence, by Lemma 2, R(G,H,E2,F2).
>
> **Case 1-2.** E1 does not match f(L1,..,Ln). Then, since E1 is ground and each variable occurs at most once in f(L1,..,Ln), there is some Li in L1,..,Ln, and some ti in t1,..,tn, such that ti does not match Li. Hence Li is not a variable, so Li=c(X1,..,Xm), c a constuctor symbol and each Xi a variable.
>
> Moreover, since R(G,H,ti,ti*), and ti does not match Li, by restriction (c), ti is not simplified. Since F1 matches f(L1,..,Ln), ti* matches Li, and so ti* is simplified. Since R(G,H,ti,ti*), ti=>ti*. Thus select(E1,ti). Hence f(t1,..,ti,..,tn) reduces to

f(t1,..,ti*,...,tn) in an N-step.

Hence there exists an N-reduction E1=P1,P2,P3,... such that for each i, Pi=f(s1,..,sn), and for each sk in s1,..,sn, sk=tk or sk=tk*. Moreover, Pi+1 is derived from Pi by selecting some sk in s1,..,sn such that sk does not match Lk in L1,..,Ln, and replacing sk, in Pi, by tk*. We also have for each i, R(G,H,Pi,F1). Since n is finite, this reduction cannot be infinite and must end in Pm such that Pm matches f(L1,..,Ln) with substitution σ. Then Pm=>RHSσ. Hence we have the N-reduction E1,P2,P3,..,Pm,RHSσ. Take E2=RHSσ. By Lemma 3, F1 and f(L1,..,Ln) match with some substitution, and clearly this is τ. Already, F2=RHSτ. By Lemma 2, R(G,H,E2,F2).

Case 2. Not F1=>F2. We are given that F1 reduces to F2 by an N-step. We now have to show that there is an N-reduction E1,..,E2 such that R(G,H,E2,F2).

Suppose select(F1,u). Then u occurs in some ti*. That is, there is some ti* in t1*,..,tn*, such that select(ti*,u). Let u=>v and let ti** be the result of replacing u in ti* by v. Hence ti* reduces to ti** in an N-step, and also F2=f(t1*,..,ti**,..,tn*). By definition of select, there is a rule f(L1,..,Li,..,Ln)=>RHS in P such that ti* does not match Li. Hence Li=c(X1,..,Xm), m>=0, where c is a constructor symbol and each Xi is a variable.

Clearly, ti* is not simplified. So, by restriction (b) ti is also not simplified. ti* reduces to ti** in an N-step. We already have R(G,H,ti,ti*). Since the length of ti is less than that of f(t1,..,ti,..,tn), by induction hypothesis there is an N-reduction ti=d1,d2,..,dr, r>=1, such that R(G,H,dr,ti**). By Lemma 4, the sequence f(t1,..,ti-1,ti,ti+1,..,tn), f(t1,..,ti-1,d2,ti+1,..,tn),.., f(t1,..,ti-1,dr,ti+1..,tn) is an N-reduction. Take E2=f(t1,..,ti-1,dr,ti+1..,tn). We already have F2=f(t1*,..,ti**,..,tn*) and for each k, R(G,H,tk,tk*). Hence R(G,H,E2,F2). **QED.**

Lemma 5. Let P be an F* program. Let R(G,H,E0,F0) and F0,F1,..,Fn be an N-reduction. Then there is an N-reduction E0,..,E1,..,En such that R(G,H,En,Fn).

Proof. By induction on length n of F0,F1,..,Fn. If n=0 then clear. Otherwise assume lemma for the N-reduction F1,..,Fn. Since F0 reduces to F1 in an N-step and R(G,H,E0,F0), by Theorem 1, there exists an N-reduction E0,..,E1 such that R(G,H,E1,F1). By induction hypothesis, there exists an N-reduction E1,..,En, such that R(G,H,En,Fn). Hence there exists the N-reduction E0,..,E1,..,En such that R(G,H,En,Fn). **QED.**

Theorem 2. Reduction-completeness of F* for simplified forms. Let P be an F* program and D0 a term. Let D0,D1,..,Dn, n>=0, be a successful reduction in P. Then

there is a successful N-reduction D0,E1,..,Em in P, such that Em-*>Dn.

Proof. By induction on length n of D0,D1,..,Dn. If n=0, D0 is already simplified, so D0 is a successful N-reduction, and D0-*>D0.

Let n>0 and assume Theorem for D1,..,Dn. Then there is a successful N-reduction D1,F2,..,Fp such that Fp-*>Dn. The situation can be laid out as follows:

```
Dn
:
:
D2
|
D1->F2-*>Fp
|
|          R(G,H,Em,Fp) ,  Fp-*>Dn
|
D0->E1-*>Em
```

Since D0->D1, there are terms G,H, such that G=>H and D1=D0[G/H]. Hence R(G,H,D0,D1). Since D1,F2,..,Fp is a successful N-reduction, by Lemma 5, there is an N-reduction D0,E1,..,Eq such that R(G,H,Eq,Fp). If Eq is simplified, take Em=Eq. Now D0,E1,..,Em is a successful N-reduction. Since R(G,H,Em,Fp), and Fp-*>Dn, Em-*>Dn, as required.

If Eq is not simplified, then since R(G,H,Eq,Fp), and Fp is simplified, Eq=>Fp. Now take Em=Fp, so D0,E1,..,Eq,Em is a successful N-reduction, and Em-*>Dn, as required. **QED.**

Theorem 3. Let P be an F* program. Let E1,F1,F2,G,H be terms such that

    (1) R(G,H,E1,F1), and
    (2) F1 reduces to F2 in an NR-step

Then there is an NR-reduction E1,..,E2 in P such that R(G,H,E2,F2).

Proof. By induction on length of E1. Let E1 be a 0-ary function symbol. If E1=F1 then clear. If E1≠F1, then E1=G, and so, clear. Otherwise, let E1=f(t1,..,tn), n>0. Assume theorem for t1,..,tn.

Case 1. E1 is unsimplified. If F1 is simplified, then since R(G,H,E1,F1), E1=G, so the

theorem is clear. If F1 is unsimplified, then by definition of NR-reduction, F1 reduces to
F2 in an N-step. By Theorem 1, there exists an N-reduction E1,..,E2 such that
R(G,H,E2,F2). But this is also an NR-reduction.

Case 2. E1 is simplified. Then, since R(G,H,E1,F1), F1 is also simplified. Let
F1=f(s1,..,sn) where f is a constructor symbol. Hence for each i, 1=<i=<n, R(G,H,ti,si).
Since F1 reduces to F2 in an NR-step, there is some si in s1,..,sn, such that si reduces to
some si* in an NR-step and F2=f(s1,..,si*,..,sn). By induction hypothesis, there exists an
NR-reduction ti=ti1,ti2,..,tik such that R(G,H,tik,si*). It can easily be shown that the
reduction f(t1,..,ti1,..,tn), f(t1,..,ti2,..,tn), .., f(t1,..,tik,..,tn) is also an NR-reduction. Clearly
R(G,H,f(t1,..,tik,..,tn),F2). **QED.**

Lemma 6. Let P be an F* program. Let R(G,H,E0,F0) and F0,..,Fn, n>=0, be an NR-
reduction. Then there is an NR-reduction E0,..,Ek such that R(G,H,Ek,Fn).

Proof. Similar to that of Lemma 5. **QED.**

Theorem 4. Reduction-completeness of F* for normal forms. Let P be an F* program
and D0 a term. Let D0,D1,..,Dn, n>=0, be a reduction in P, where Dn is in normal form.
Then there is an NR-reduction D0,E1,..,Em=Dn, m>=0, in P.

Proof. By induction on length n of D0,D1,..,Dn. If n=0, D0 is already in normal form, so
D0 is the required NR-reduction.

Let n>0 and assume theorem for D1,..,Dn. Then there is an NR-reduction
D1,F2,..,Fp=Dn. The situation can be laid out as follows:

```
Dn (in normal form)
:
|
D2
|
D1->F2-*>Fp=Dn
|
D0->E1-*>Em
```

Since D0->D1 there are terms G,H, such that G=>H and D1=D0[G/H]. Hence
R(G,H,D0,D1). Since D1,F2,..,Fp is an NR-reduction, by Lemma 6, there is an NR-
reduction D0,E1,..,Eq such that R(G,H,Eq,Fp). It is easily shown, by induction on length
of terms, that there is an NR-reduction Eq,..,Fp. In each step in it, an occurrence of G is
replaced by H. The required NR-reduction is then D0,E1,..,Eq,..,Fp=Dn=Em. **QED.**

III. DETERMINISTIC F*

III.1 INTRODUCTION

A class of F* programs called **Deterministic F* (DF*)** is now defined and shown to possess several useful computational properties. In particular, every DF* program satisfies confluence and directedness. Confluence is shown to hold for any F* program which satisfies just restriction (f) below.

Confluence, means that if for terms M,N,P, M-*>N, and M-*>P, then there exists term Q such that N-*>Q, and P-*>Q. It has the immediate consequence that every term has at most one normal form. Hence DF* can be used as a functional programming system. Also, if a DF* program is interpreted as an equality theory, equality of two terms can be determined by checking whether their normal forms are syntactically identical.

Directedness, for simplified forms, means that if a term has a simplified form then *any* N-reduction starting at that term, if extended far enough, computes it. Moreover, all successful N-reductions are of equal length. Directedness, for normal forms, means that if a term has a normal form, then *any* NR-reduction starting at that term, if extended far enough, computes it. Moreover, all NR-reductions ending in normal forms are of equal length. Due to directedness, no searching among alternative N- or NR-reductions is necessary.

III.2 DEFINITION OF DF*

A DF* program is an F* program P satisfying two restrictions:

(f) Let LHS1 and LHS2 be variants of heads of two rules in P, such that LHS1 and LHS2 have no variables in common. Then LHS1 and LHS2 do not unify.

(g) Let f(L1,..,Li,..,Lm)=>RHS be a rule in P, where Li is not a variable. Then in every other rule f(K1,..,Ki,..,Km)=>RHS1 in P, Ki is not a variable.

Again, as can be seen from examples in this paper, and especially in Section VI, DF* is also quite expressive. Note that restrictions (a)-(e) are upon rules while (f) and (g) are upon the entire program. In the following, the first three rules do not constitute a DF* program because they violate (f) and the next four do not because they violate (g):

        insert(A,[])=>[A].
        insert(A,[U|V])=>[A,U|V].
        insert(A,[U|V])=>[U|insert(A,V)].

```
f(X,[])=>[].
f([],[U|V])=>[].
a=>a.
b=>[].
```

Restriction (f), supported by (a)-(e), ensures confluence. Restriction (g), supported by (a)-(f), ensures directedness. In particular, given a term f(t1,..,ti,..,tn), it is possible to determine, at compile time, whether ti needs to be simplified. It needs to be, only if the ith argument in the head of any F* rule defining f is a non-variable. Moreover, as shown below, the arguments of f which do need to be simplified can be simplified in any order.

The importance of select may be emphasized from the observation that even with restrictions (a)-(g), every outermost reduction strategy is not reduction complete. For example, given the DF* program:

```
g([],X)=>[]
g([U|V],W)=>.    ..  `
```

and the term E=g(b,a), a rightmost-outermost reduction strategy would compute the infinite reduction g(b,a),g(b,a),.... However, there exists a successful leftmost-outermost reduction g(b,a),g([],a),[]. Select, of course, would compute this second reduction.

Thus, select is more than an outermost reduction strategy. For DF*, it may perhaps be called *outermost-call-by-need*. Note that it is still non-deterministic. However due to directedness, the non-determinism is benign.

$S_P(A,B)$. Let P be an F* program, and A,B be terms. Let G1,..,Gm, m>=0, be mutually non-overlapping subterms in A, and H1,..,Hm be terms such that for each i=<m, Gi=>Hi, and B is the result of *simultaneously* replacing G1,..,Gm, in A, by respectively, H1,..,Hm. Then we say $S_P(A,B)$. Note that G1,..,Gm need not include all, or even one, of the mutually non-overlapping subterms of A which reduce as a whole. The subscript on S is dropped if clear from context.

R@i. Let R be an N-reduction E0,E1,..,Em, m>=0, where for no i, Ei=>Ei+1. Then there is some function symbol f, such that each Ei is of the form f(p1,..,pk). Let E0=f(t1,..,tk), and for any p, let Rp be E0,E1,..,Ep.

For any 1=<i=<k, R0@i is defined to be the singleton sequence ti. For any j≠m, let Ej=f(a1,..,an-1,an,an+1,..,ak), and Ej+1=f(a1,..,an-1,bn,an+1,..,ak) such that an reduces to bn in an N-step. If n=i, then Rj+1@i=Rj@i:bn, otherwise, Rj+1@i=Rj@i. Here : is concatenation of a term at the end of a sequence of terms.

For example, with the rules a=>a, b=>b1, b1=>b2, and the N-reduction R=f(a,b),f(a,b1), f(a,b1),f(a,b2), R@1=a,a, and R@2=b,b1,b2. Thus, roughly, R@i is the sequence, without duplicates, of ith arguments of the outermost function symbol of the members of the N-reduction R.

R@u. R@u is a generalization of R@i to positions in terms. Let R be an NR-reduction E0,E1,..,Em, m>=0, where E0 is simplified. Let A0,A1,..,Ap be unsimplified terms in E0 such that no Ai is properly contained in any other unsimplified term. Let the positions of A0,A1,..,Ap, in E0 be u1,..,up respectively. Then, for each j≠m, Ej+1 can be thought of as being derived from Ej by replacing a term A at one of the ui, by another term B. Moreover, A reduces to B in an NR-step.

For any ui in u1,..,up, R0@ui is defined to be the singleton sequence Ai. For any j, j≠m, let Ej+1 be derived from Ej by replacing a term P at position u in Ej by Q, where u is in u1,..,up. If u=ui, Rj+1@ui=Rj@ui:Q, otherwise, Rj+1@ui=Rj@ui.

III.3 CONFLUENCE AND DIRECTEDNESS OF DF*

Confluence and directedness are shown by deriving the following results, for any DF* program P:

(a) Let F1,E1,F2 be terms such that S(F1,E1), and F1->F2. Then there exists a term E2 such that E1-*>E2, and S(F2,E2).

(b) If there are two N-reductions starting at the same term and ending in terms in simplified form, then these terms are identical, and the N-reductions are of equal length.

(c) Let E0,E1,..,En be a successful N-reduction. Let E0=F0,F1,..,Fp, be an *unsuccessful* N-reduction, i.e. Fp is not simplified. Then p<n, and there exists Fp+1 such that Fp reduces to Fp+1 in an N-step.

Now, (a) is iterated to obtain confluence. (c) requires (b). From (c) we infer that if a term E0 has a successful N-reduction then no N-reduction starting at E0 is infinite, or terminates in failure. Hence, every N-reduction must terminate in a term in simplified form. Hence directedness for simplified forms. Similarly, directedness for normal forms.

Lemma 1. Select never chooses overlapping terms. Let P be a DF* program. Let E and F be terms such that select(E,F). Then, for all G, select(E,G) implies that G is not properly contained in F.

Proof. By induction on length of E. As before, the definition of select, for any term f(T1,..,Tn) is:

$select_p$(f(T1,..,Tn),f(T1,..,Tn)) if f(T1,..,Tn)=>$_p$X.

$select_p$(f(T1,..,Ti,..,Tn),X) if

there is a rule f(L1,..,Li,..,Ln)=>RHS in P, and

there is no substitution σ such that Ti=Liσ, and

$select_p$(Ti,X).

If E is a 0-ary function symbol, the lemma holds. Otherwise let E=f(t1,..,ti,..,tm) and let the lemma hold for each of t1,..,tm. Suppose select(E,F) but F≠E. Then for some ti in t1,..,tm, select(ti,F). Suppose select(E,G). If G=E then G is clearly not contained in F. Otherwise, for some tj in t1,..,tm, select(tj,G). If j=i, by induction hypothesis, G is not properly contained in F. If j≠i, of course, G is not properly contained in F.

Suppose select(E,F) and F=E. Then there exists a rule f(M1,..,Mi,..,Mm)=>RHS such that E matches its head. Now suppose that there also exists G such that select(E,G), and G is properly contained in F. Hence, for some ti in t1,..,tm, select(ti,G). Hence there is a rule f(L1,..,Li,..,Lm)=>RHS1 such that ti does not match Li. Hence Li is not a variable. By restriction (g) Mi is also not a variable. Hence ti is in simplified form. But then select(ti,G) fails. Contradiction. **QED.**

Lemma 2. Let P be a DF* program. Let G be a term. Then there is at most one term H such that G=>H.

Proof. By restriction (f). **QED.**

Lemma 3. Let σ and τ be two substitutions each defining only the variables X1,..,Xm, m>=0, such that for any i=<m, where <Xi,si> appears in σ, and <Xi,ti> in τ, S(si,ti). Let M be a term, possibly containing variables, but only from X1,..,Xm. Then S(Mσ,Mτ).

Proof. By induction on length of M. **QED.**

Lemma 4. Let P be a DF* program. Let A=f(t1,..,tm), m>0, and B=f(t1*,..,tm*), such that for each i=<m, S(ti,ti*). Let A=>C. Then there exists D, such that B=>D and S(C,D).

Proof. Let A reduce to C by the rule LHS=>RHS. Then, there exists a substitution σ such that A=LHSσ and C=RHSσ. It is easily verified that there exists substitution τ such that B=LHSτ, σ and τ define the same variables, and for each i, where <Xi,pi> appears in σ and <Xi,qi> in τ, S(pi,qi). Hence B=>RHSτ=D. By Lemma 3, S(C,D). **QED.**

Lemma 5. Let P be a DF* program. Let F1,E1,F2 be terms such that S(F1,E1), and F1->F2. Then there exists term E2 such that E1-*>E2, and S(F2,E2).

Proof. By induction on length of F1. The situation can be visualized in the following diagram:

```
            F1
           / \
          *    \
         /      \
      E1        F2      S(F1,E1),  F1->F2
        \      /
         *    *
          \ /
          E2
```

Case 1. F1 is a 0-ary function symbol. Since F1->F2, F1=>F2. If F1=E1, take E2=F2. Then E1=>E2, and S(F2,E2), as required. Otherwise, F1=>E1. By restriction (f), E1=F2. Take E2=F2. Again, E1-*>E2, and S(F2,E2), as required.

Case 2. F1=f(t1,..,tm), m>0. Assume Lemma for t1,..,tm.

    Case 2-1. F1 reduces to E1 as a whole. If F1 reduces to F2 as a whole, by restriction (f), F2=E1. Take E2=E1. Then E1-*>E2, and also S(F2,E2), as required. Otherwise, there is some j=<m, such that tj->tj*, and F2=f(t1,..,tj*,..,tm). Hence S(F1,F2). By Lemma 4, there exists E2 such that F2=>E2 and S(E1,E2). But then E1-*>E2. Since F2=>E2, S(F2,E2), as required.

    Case 2-2. F1 does not reduce as a whole to E1. Then E1=f(s1,..,sm), and for each i=<m, S(ti,si).

    If F1=>F2, then, by Lemma 4, there exists E2 such that E1=>E2, and S(F2,E2), as required. Otherwise, there is some j=<m, such that tj->tj*, and F2=f(t1,..,tj-1,tj*,tj+1,..,tm). By induction hypothesis, there exists p, such that sj-*>p and S(tj*,p). Take E2=f(s1,..,sj-1,p,sj+1,..,sm). Clearly, E1-*>E2, and also, S(F2,E2), as required. **QED.**

Lemma 6. Let P be a DF* program, and M,N,P be terms such that S(M,N) and M-*>P. Then there exists term Q such that N-*>Q and S(P,Q).

Proof. By iterating Lemma 5. **QED.**

Lemma 7. Let P be a DF* program, and M,N,P be terms such that M->N, and M-*>P. Then there exists term Q such that N-*>Q, and P-*>Q.

Proof. Since M->N, S(M,N). By Lemma 6, there exists term Q such that N-*>Q and S(P,Q). Hence P-*>Q, as required. **QED.**

Theorem 1. Confluence of DF*. Let P be a DF* program, and M,N,P be terms such that M-*>N, and M-*>P. Then there exists term Q such that N-*>Q, and P-*>Q.

Proof. By iterating Lemma 7. **QED.**

Corollary. Uniqueness of normal forms. Let P be a DF* program. Then every term has at most one normal form.

Lemma 8. Let R be an N-reduction f(p1,..,pk)=E0,E1,..,Em such that for no i, Ei=>Ei+1. Then the length m of E0,E1,..,Em is equal to the sum of the lengths of R@1, R@2,..,R@k.

Proof. By induction on m. If m=0, then clear. Assume lemma for E0,..,Em-1. There exists exactly one n, such that Em-1=f(t1,..,tn-1,tn,tn+1,..,tk), Em=f(t1,..,tn-1,un,tn+1,..,tk), and tn reduces to un in an N-step. So, for every i, i≠n, (E0,..,Em-1)@i=(E0,..,Em-1,Em)@i. Only for n, (E0,..,Em-1,Em)@n=(E0,..,Em-1)@n:un. By induction hypothesis, the lemma is clear. **QED.**

Lemma 9. Let P be a DF* program. Let E0,E1,..,En be a successful N-reduction. Then for every successful N-reduction E0,F1,..,Fp, p=n and Fp=En.

Proof: By induction on n. If n=0 then E0 is simplified and the lemma holds trivially. Let n>1. Assume hypothesis for all successful N-reductions of length less than n.

Since E0,E1,..,En is a successful N-reduction, there exists Ek, 0=<k<n, such that for no i, 0=<i<k, Ei=>Ei+1, but Ek=>Ek+1, and Ek+1,..,En is a successful N-reduction. Let E0=f(t1,..,tm), m>=0. Since n>0, f is not a constructor symbol. Then Ek=f(s1,..,sm) for terms s1,..,sm. Similarly, for the successful N-reduction F0,F1,..,Fp, there exists Fj with properties similar to those of Ek. The situation can be laid out in the following diagram:

```
E0=f(t1,..,tm)----*>Ek=f(s1,..,sm)=>Ek+1--*>En

F0=f(t1,..,tm)----*>Fj=f(q1,..,qm)=>Fj+1--*>Fp
```

Consider any ti in t1,..,tm.

Case 1. ti is simplified. Then, by definition of select, ti=si. Similarly, ti=qi. Hence qi=si.

Case 2. ti is unsimplified. If si is simplified, then there exists a successful N-reduction (E0,..,Ek)@i, of length less than n.

By restriction (g), the ith argument in the head of any rule in P, defining f, is a non-variable. Hence, qi is also simplified. Hence there exists a successful N-reduction (F0,..,Fj)@i. By induction hypothesis, its length is equal to that of (E0,..,Ek)@i, and qi=si.

If si is unsimplified, then, by restriction (g), and definition of select, ti=si=qi.

Hence Ek=Fj. By Lemma 8, the length of E0,..,Ek is the sum of lengths of (E0,..,Ek)@i such that ti is unsimplified but si is simplified. Again, by Lemma 8, and **Case 2**, this is also the length of F0,..,Fj. Hence, k=j. By restriction (f), Ek+1=Fj+1. Now, Ek+1,..,En, is a successful N-reduction of length less than n. By induction hypothesis, its length is equal to that of the successful N-reduction Fj+1,..,Fp, and En=Fp. Hence, also, the length of E0,..,En is equal to that of F0,..,Fp. **QED.**

Lemma 10. Let P be a DF* program. Let E0,E1,..,En and E0=F0,F1,..,Fm be two NR-reductions such that En and Fm are in normal form. Then En=Fm and n=m.

Proof: Note that En=Fm follows directly from the confluence of DF*. We focus on showing that n=m, and proceed by induction on length of E0,E1,..,En. If n=0, then clear. Otherwise, let n>0 and assume the lemma for NR-reductions of length less than n.

Case 1. E0 is unsimplified. Then, there exists Ek, 0<k=<n such that E0,..,Ek is a successful N-reduction. Also, there exists Fj, 0<j=<m such that E0,..,Fj is a successful N-reduction. By Lemma 9, Fj=Ek and j=k. Now Ek,..,En, and Fj,..,Fm are also NR-reductions. The length of Ek,..,En is less than n, so by induction hypothesis, n=m.

Case 2. E0 is simplified. Then E0=c(t1,..,tq) for terms t1,..,tq and constructor symbol c. If E0 is in normal form, then the theorem holds. Otherwise, let A0,A1,..,Ap be unsimplified terms in E0 such that no Ai is properly contained in any unsimplified term. Consider any Ai in A0,A1,..,Ap.

Let the position at which Ai occurs in E0 be ui. Then, since En is in normal form, (E0,..,En)@ui is an NR-reduction ending in a normal form. Similarly obtain (F0,..,Fm)@ui.

By reasoning as in **Case 1**, the length of (E0,...,En)@ui is equal to that of (F0,...,Fm)@ui. It can be shown, analogously to Lemma 8, that the length of E0,...,En is equal to the sum of the lengths of each (E0,...,En)@ui. Similarly, for length of F0,...,Fm. Hence m=n. **QED.**

Lemma 11. Let P be a DF* program and E0 a term. Let E0,E1,...,En be a successful N-reduction. Let E0=F0,F1,...,Fp, be an *unsuccessful* N-reduction, i.e. Fp is not simplified. Then p<n, and there exists Fp+1 such that Fp reduces to Fp+1 in an N-step.

Proof: By induction on the length of E0,...,En. If n=0 then E0 is in simplified form and the only N-reduction starting at E0 is E0 itself, so the lemma is clear. Let n>0. Then E0 is not simplified. Assume lemma for all successful N-reductions of length less than n. Since E0,E1,...,En is a successful N-reduction, there exists Ek, 0=<k<n such that for no i, 0=<i<k, Ei=>Ei+1, but Ek=>Ek+1, and Ek+1,...,En is a successful N-reduction. Let E0=f(t1,...,tm), m>=0. Let Ek=f(s1,...,sm). We have two cases:

Case 1. There exists Fj, 0=<j<p such that for no i, 0=<i<j, Fi=>Fi+1, but Fj=>Fj+1, and Fj+1,...,Fp is an N-reduction. Let Fj=f(q1,...,qm). The situation can be visualized in the following diagram:

```
E0=f(t1,..,tm)--*>Ek=f(s1,..,sm)=>Ek+1--*>En

F0=f(t1,..,tm)--*>Fj=f(q1,..,qm)=>Fj+1--*>Fp
```

By reasoning as in Lemma 9 above, Ek=Fj, and k=j. By restriction (f), Ek+1=Fj+1. By induction hypothesis, p<n. Furthermore, there exists Fp+1 such that Fp reduces to Fp+1 in an N-step.

Case 2. There does not exist Fj in F0,...,Fp such that Fj=>Fj+1. Let Fp=f(q1,...,qm). The situation can be visualized as:

```
E0=f(t1,..,tm)--*>Ek=f(s1,..,sm)=>Ek+1--*>En

F0=f(t1,..,tm)--*>Fp=f(q1,..,qm)  (unsimplified)
```

It is easily seen that either Fp=>Fp+1, or there exists i in 1,...,m such that qi is not simplified, but si is. By induction hypothesis, there exists ri such that qi reduces to ri in an N-step. Hence Fp reduces to f(q1,...,ri,...,qm) in an N-step. Also, by Lemma 8, and induction hypothesis, p<n. **QED.**

Theorem 2. Directedness for simplified forms. Let P be a DF* program. Let E0

be a term and let E0,..,En be a successful reduction. Then any N-reduction starting at E0, if extended far enough, would terminate in a term in simplified form.

Proof. By reduction-completeness for simplified forms, (Theorem 2, Section II), and iterating Lemma 11. **QED.**

Lemma 12. Let P be a DF* program and E0 a term. Let E0,E1,..,En be an NR-reduction such that En is in normal form. Let E0=F0,F1,..,Fp, be an NR-reduction such that Fp is not in normal form. Then, p<n, and there exists Fp+1 such that Fp reduces to Fp+1 in an NR-step.

Proof: By induction on length of E0,E1,..,En. If n=0, then clear. Otherwise, assume Lemma for all NR-reductions of length less than n, and ending in normal forms.

Case 1. E0 is unsimplified. By a reasoning very similar to that in proof of Lemma 11.

Case 2. E0 is simplified. If E0 is in normal form, the lemma trivially holds. Otherwise, as in Case 2 of Lemma 10. **QED.**

Theorem 3. Directedness for normal forms. Let P be a DF* program. Let E0 be a term and let E0,..,En be a reduction where En is in normal form. Then any NR-reduction starting at E0, if extended far enough, would terminate in a normal form.

Proof By reduction-completeness for normal forms, (Theorem 4, Section II), and iterating Lemma 12. **QED.**

IV. LABELED DETERMINISTIC F*

IV.1 INTRODUCTION

Intuitively, it can be seen that in an N-reduction a term is reduced only when it is necessary for simplifying the first term in the reduction. In this sense, an N-reduction conserves computation. For example, with the rules:

    f(X)=>[X].
    a=>[].

there exists the N-reduction f(a),[a]. There is no N-reduction starting at f(a) in which a is reduced. However, it can also happen that in an N-reduction, several copies of the same term are reduced. This can happen when use is made of a rule in which a variable occurs more than once on the right hand side. In this sense, an N-reduction wastes computation. For example, with the rules:

    f(X)=>g(X,X).
    g([],[])=>[].
    a=>[].

there exists the N-reduction f(a),g(a,a),g([],a),g([],[]),[]. The two occurrences of a in the second term are copies of each other, yet they are reduced separately. This is the same problem which arises with a call-by-name procedure call mechanism in programming languages.

If we can arrange that when a term is reduced, all copies of it are also reduced, then N-reductions could become considerably shorter. In fact, it is shown that they become *minimal*. An N-step in which all copies of a term are replaced is called an NA-step. Thus it is distinguished from an N-step in which only a single copy of a term is replaced. A sequence of NA-steps is called an NA-derivation. The prefix NA stands for "normal-all". Minimality yields a strong form of laziness, since terms are simplified with minimum computational effort.

The notion of a copy of a term, however, has two legitimate interpretations. The first is simply that any two occurrences of a subterm in a term are copies of each other.

The second is obtained from examining representations of terms as directed acyclic graphs. A 0-ary function symbol f is represented as a graph consisting of just a single node with f stored in it. A term f(t1,..,tn) is represented as a graph whose root is a node with n+1 fields. The first field stores f and for each $1 =< i =< n$, the ith field stores a pointer

to the graph representation of ti. A term can have many graph representations. For example, the two occurrences of a in f(a,a) can be represented by a single graph, or by distinct graphs. Now, two occurrences of a subterm in term E are said to be copies of each other *only* if, in the graph representation of E, they have the same graph representation.

We adopt the second interpretation since it enables us to develop a simple proof of minimality and also to implement replacement of all copies of a subterm with a small overhead. Graph representations of terms are, in turn, represented using labeled terms. The address of each node in a graph is represented by a label. Let there be a graph G with root node N. Let N contain m+1 fields, where the first field contains the symbol f and the rest of the m fields contain pointers to, respectively, graphs G1,..,Gm. Let the address of N be represented by label α. Then the representation of G is the labeled term f(α,t1,..,tm) where for each i, the representation of Gi is the labeled term ti.

A subset of DF* called, Labeled Deterministic F* (LDF*), is defined. Notions of labels [Vuillemin 1974], labeled terms, ordinary terms, and ordinary programs are introduced. Reductions in LDF* are intended to mimic graph reduction. In particular, it is ensured that when a new node is allocated in graph reduction, a label not previously used in the LDF* reduction is generated.

LDF* is shown to be minimal in the following sense: where P* is an LDF* program, and E a proper term, let there be a shortest successful reduction of E. Then there is a successful NA-derivation of E of lesser or equal length.

It is also shown that with each ordinary DF* program P, one can associate an LDF* program P*, such that if there is a successful reduction in P, there is a successful reduction in P* of exactly equal length. Hence, to simplify terms in P in a minimum number of steps, it is sufficient to transform P to P* and use NA-derivations.

Some main ideas in our proof are (a) in each reduction step, a label is eliminated, so (b) the size of the elimination-set (E-set) of a reduction, i.e. the set of labels eliminated in the reduction, is a lower-bound on its length, (c) the size of the E-set of an NA-derivation of a proper term, is exactly equal to its length.

IV.2 DEFINITION OF LDF*

Labels. Let α, β, ξ, α1, β1, ξ1,.. be an enumerably infinite subset of the set of 0-ary function symbols in F*. Each member of this list is called a primitive label.

Let * be a binary function symbol in F*. A label is defined as follows. A primitive label

is a label. If x and y are labels then x*y is also a label. A label α is said to be a proper
initial segment of label β if either $\beta=\alpha*\delta$, or $\beta=\xi*\delta$ and α is a proper initial segment of ξ.

Labeled terms. Where f is an n+1-ary function symbol, n>=0, f≠*, α a label and t1,..,tn
labeled terms, $f(\alpha,t1,..,tn)$ is a labeled term. α is called the outermost label of $f(\alpha,t1,..,tn)$.

For example, where f is a 4-ary function symbol and a,b are 1-ary function symbols,
$f(\delta,a(\alpha),b(\beta),a(\xi))$ is a labeled term, and δ is the outermost label of this term. Note that a
label standing alone is *not* a labeled term. Neither is a labeled term of the form A*B.
Also, note that a labeled term never contains any variables.

A labeled term is said to be in normal form if it contains only constructor symbols and
labels.

Maximal labels. A label is maximal in a labeled term if it is not a proper initial segment
of any other label in that term.

Proper terms. A labeled term E is called proper if (a) all its labels are maximal, and (b)
for every two subterms A and B of E, if A and B have the same outermost label then
A=B. For example, $f(\alpha,b(\xi),c(\delta))$ is a proper term. However, $g(\alpha,a(\alpha*\delta))$ is not a proper
term since it violates (a), and $f(\alpha,b(\alpha))$ is not a proper term since it violates (b).

Ordinary terms, ordinary rules, and ordinary programs. A term in F*, possibly
containing variables, a rule in F*, or an F* program, is said to be ordinary if it does not
contain any labels, nor any occurrence of the symbol *.

A mapping Σ. Let F be the set of all function symbols in F*, except *, and the primitive
labels. Let there be an injection Σ between F and F which maps each n-ary function
symbol in F to an n+1-ary function symbol in F. Moreover, Σ always maps a constructor
symbol to a constructor symbol, and a non-constructor symbol to a non-constructor
symbol.

Labeled versions of ordinary terms, possibly containing variables. Let E be an
ordinary term, possibly containing variables. If E is a variable then its labeled version is
E itself. Otherwise, let E=f(t1,..,tn), n>=0. Its labeled version is $f\_(\alpha,t1\_,..,tn\_)$ where α
is a label, $\Sigma(f)=f\_$, and for each i, $ti\_$ is a labeled version of ti. For example, where Σ
maps f to f_ and a to a_, a labeled version of f(a,a) is $f\_(\alpha,a\_(\beta),a\_(\delta))$.

Labeled versions of ordinary rules. Let LHS=>RHS be an ordinary F* rule. A labeled
version of this rule, LHS*=>RHS*, is defined as follows:

Let LHS=f(L1,..,Lm). Then LHS*=f_(L,L1_,..,Lm_) satisfying the following conditions: (a) f_=Σ(f), (b) L is a variable, (c) If Li is a variable, Li_=Li, otherwise Li=c(X1,..,Xm), and Li_=c_(Ki,X1,..,Xm), Ki a variable, Σ(c)=c_, and (d) a variable occurs at most once in LHS*.

Let RHS1 be a labeled version of RHS in which all labels are distinct, and for no two of these is one a proper initial segment of the other. Let these labels be β1,..,βk. Then, where LHS*=f(L,L1_,..,Lm_), RHS* is obtained by replacing, in RHS1, each βi by L*βi.

Labeled Deterministic F* Programs. Let P be an ordinary DF* program, and let P* consist of labeled versions of rules in P. Then P* is called a labeled deterministic F* (LDF*) program. For example, where P consists of:

    append(nil,X)=>X
    append(cons(U,V),W)=>cons(U,append(V,W))

and Σ maps append, nil, and cons to append_, nil_ and cons_ respectively, P* consists of:

    append_(L,nil_(L1),X)=>X.
    append_(L,cons_(K1,U,V),W)=>cons_(L*β1,U,append_(L*β2,V,W))

where β1, and β2 are distinct labels, and neither is a proper initial segment of each other. Note that each LDF* program is a DF* program as well as an F* program. Also, each labeled term is an F* term. *Hence, results of all previous sections also hold for LDF* programs and labeled terms.*

NA-steps and NA-derivations. Let P be an LDF* program and E,G,H be labeled terms. Suppose select$_P$(E,G) and G=>$_P$H. Let E1 be the result of replacing *all* occurrences of G by H in E. Then we say that E reduces to E1 in an NA-step in P. The prefix NA in N-step stands for "normal-all". A sequence of labeled terms E0,E1,... is an **NA-derivation** if for each i, when Ei, and Ei+1 both exist, Ei reduces to Ei+1 in an NA-step. For example, given the rule a(L)=>b(L*α), the term f(β,a(δ),a(δ)) reduces in an NA-step to f(β,b(δ*α), b(δ*α)).

Leftmost steps and reductions. Let P be an F* program, not necessarily ordinary. Let E be a term, and G and G1 two of its subterms. G is said to be to the left of G1 in E, if either (a) they both occur at the same position in E, or (b) in the depth-first or preorder traversal of the tree representation of E, the function symbol which is the root of G occurs before the function symbol which is the root of G1.

Let select(E,G), G=>H. Then E reduces to F in a leftmost N-step, if for every G1,

select(E,G1) implies G is to the left of G1 in E, and F=E[G/H].

Let select(E,G), G=>H. Then E reduces to F in a leftmost NA-step, if for every G1, select(E,G1) implies G is to the left of G1 in E, and F is the result of replacing all occurrences of G in E by H.

Definitions of leftmost N-reductions and leftmost NA-derivations are the obvious ones.

Elimination sets or E-sets. Let A0,A1,..,An be a reduction where each Aj is a labeled term. For any i, let Ai+1=Ai[G/H] where G=f(α,t1,...,tm). Then we say that the function-label pair (FL-pair) <f,α> has been eliminated in the reduction Ai,Ai+1. The elimination set or E-set of a reduction is defined as the set of all FL-pairs eliminated in the reduction. Since elimination of an FL-pair requires one reduction step, the size of this set (number of elements in it) is a lower bound on the length of the reduction (the number of steps in it).

Since an NA-step can be thought of as a sequence of reductions steps, an NA-derivation can be thought of as a reduction. Hence, the E-set of an NA-derivation is the E-set of the corresponding reduction.

IV.3 MINIMALITY OF LDF*

Let P be an LDF* program and E a labeled term. We already know from completeness of DF* that if E has a successful reduction, it has a successful N-reduction. By directedness of DF*, it has a successful leftmost N-reduction. We now show the following:

(a) If E has a successful reduction R0, E has a successful N-reduction R1 whose E-set is a subset of the E-set of R0.

(b) If R1 and R2 are two successful N-reductions of E, their E-sets are identical.

(c) If E has a successful leftmost N-reduction R2, it has a successful leftmost NA-derivation R3. Furthermore, the E-set of R3 is a subset of the E-set of R2.

(d) If E is a proper term, the size of the E-set of any NA-derivation starting at E is equal to the number of NA-steps in that derivation.

(e) Let P be an ordinary DF* program, and P* its labeled version. Let E0 be an ordinary term, and E0* a labeled version of E0. Let E0,E1,E2,... be a reduction in P. Then there exists a reduction E0*,E1*,E2*,... in P*, such that for each i, Ei* is a labeled version of Ei.

Let E be a proper term. Let R0 be a shortest successful reduction of E. Then its length is greater than or equal to the size of its E-set. By (a), there exists R1, an N-reduction of E whose E-set is a subset of that of R0. By directedness of DF*, there exists R2, a successful leftmost N-reduction of E. By (b), the E-set of R1 is identical to that of R2. By (c), there exists R3, a successful leftmost NA-derivation of E whose E-set is a subset of that of R2. By (d), the length of this NA-derivation is at most the length of R0. Hence, leftmost NA-derivations are minimal for simplifying proper terms.

Now, let P be an ordinary DF* program and P* its labeled version. Let there be a successful reduction R of a term E in P. By (e) there exists a successful reduction R* of a labeled version E* of E. This version can always be chosen to be proper. By minimality of LDF*, there is a successful NA-derivation starting at E* of length less than or equal to that of R* or R. Hence, to simplify terms in a minimum number of steps, it is sufficient to transform P to P* and use leftmost NA-derivations. This reasoning is now carried out formally and in detail.

IV.3.1 Existence of successful leftmost NA-derivations

Lemma 1. Let P be an LDF* program. Let E0,F0 be labeled terms such that E0->F0. If E0 reduces to E1 in a leftmost N-step then there exists F1 such that E1-*>F1, and (a) either F1=F0, or (b) F0 reduces to F1 in a leftmost N-step, and the FL-pair eliminated in F0,F1 is the same as that eliminated in E0,E1.

Proof. By induction on length of E0. We can draw the following diagram:

```
E0------> F0
|         |
leftmost  | F0=F1 or
N-step    | F0 reduces to F1 in a leftmost N-step
|         |
E1-----*> F1
```

Case 1. E0=f(α) for some 1-ary function symbol f and label α. Since E0->F0, E0=>F0. So, select(E0,E0) and due to restriction (f), E1=F0. Take F1=F0. Clearly, E1-*>F1.

Case 2. E0=f(α,t1,..,tm), for some m+1-ary function symbol f, m>0, label α, and labeled terms t1,..,tm.

    Case 2-1. E0=>F0. Similar to Case 1. E1=F1=F0 and E1-*>F1.

    Case 2-2. Not E0=>F0. Then F0=f(α,t1*,..,tm*), and there exists j such that tj-

>tj* and for each i, i≠j implies ti=ti*.

Suppose E0=>E1. Then the FL-pair eliminated in E0,E1 is <f,α>. It is easily verified by induction on length of E0, that F0=>F1 and E1-*>F1. Also, F0 reduces to F1 in a leftmost N-step. Finally, the FL-pair eliminated in F0,F1 is also <f,α>.

Suppose not E0=>E1. Then, there is some k, such that E1=f(t1,..,tk-1,sk,tk+1,..,tm), and tk reduces to sk in a leftmost N-step. By induction hypothesis, there exists sk* such that sk-*>sk*, and either tk*=sk*, or tk* reduces to sk* in a leftmost N-step, and the FL-pair eliminated in tk,sk is the same as that eliminated in tk*,sk*.

If tk*=sk*, let F1=F0. Clearly, E1-*>F1. Otherwise, let F1=f(α,t1*,..,tk-1*,sk*,tk+1*,..,tm*). Since tk* reduces to sk* in an N-step, tk* is not simplified. Hence, using restriction (g), it is easily verified that F0 reduces to F1 in a leftmost N-step. In particular, in this step, tk* reduces to sk* in a leftmost N-step. Hence, E1-*>F1, and the FL-pair eliminated in E0,E1 is the same as that eliminated in F0,F1. **QED.**

Lemma 2. Let P be an LDF* program. Let E0,F0 be labeled terms such that E0-*>F0. If E0 reduces to E1 in a leftmost N-step then there exists F1 such that E1-*>F1, and (a) either F1=F0, or (b) F0 reduces to F1 in a leftmost N-step, and the FL-pair eliminated in F0,F1 is the same as that eliminated in E0,E1.

Proof. By induction on length of the reduction E0,..,F0, and using Lemma 1. **QED.**

Lemma 3. Let P be an LDF* program. Let E0,F0 be labeled terms such that E0-*>F0 and let there be a successful leftmost N-reduction E0,E1,..,En. Then there is a successful leftmost NA-derivation F0,F1,F2,..,Fk whose E-set is a subset of that of E0,E1,..,En.

Proof. By induction on length n of E0,..,En, and using Lemma 2. **QED.**

Theorem 1. Let P be an LDF* program. Let E0 be a labeled term and E0,E1,..,En a successful leftmost N-reduction. Then there is a successful leftmost NA-derivation E0,F1,F2,..,Fk whose E-set is a subset of that of E0,E1,..,En.

Proof. Since E0-*>E0, apply Lemma 3. **QED.**

IV.3.2 E-sets of N-reductions

Lemma 4. Let P be an LDF* program and E1,F1,G,H be labeled terms such that:

    (a) R(G,H,E1,F1), and
    (b) F1 reduces to F2 in an N-step, and
    (c) The outermost function symbol and label of G are, respectively, g and α, and
    (d) <r,β> is the FL-pair eliminated in the reduction F1,F2.

Then there exists an N-reduction E1,..,E2 such that its E-set is included in {<g,α>,<r,β>} and R(G,H,E2,F2).

Proof. Exactly parallel to proof of Theorem 1, Section II. **QED**.

Lemma 5. Let P be an LDF* program. Let E1,F1,G,H, be labeled terms such that R(G,H,E1,F1). Let the outermost function symbol and label of G be g and α respectively. Let F1,F2,..,Fm be a successful N-reduction. Then there exists a successful N-reduction E1,..,En whose E-set is contained in the union of {<g,α>} and the E-set of F1,F2,..,Fm.

Proof. By induction on length of F1,..,Fm. **QED**.

Lemma 6. Let E1,F1,G2,..,Gm be a successful reduction. Then there is a successful N-reduction E1,..,En such that the E-set of E1,..,En is contained in that of E1,F1,G2,..,Gm.

Proof. By induction on length of E1,F1,G2,..,Gm, and Lemma 5. **QED**.

Lemma 7. Let P be an LDF* program. Let E0 be a labeled term and E0,E1,..,En and E0,F1,..,Fp two successful N-reductions. Then, the E-set of one is identical to that of the other.

Proof. Exactly analogous to the proof of Lemma 9, Section III, that any two successful N-reductions of a term are of equal length, and end in the same simplified form. **QED**.

IV.3.3 Reductions of proper terms

Lemma 8. Let P be an LDF* program. Let E be a proper term and let E reduce to F in an NA-step. Then all labels of F are maximal.

Proof. Let select(E,G). Then G=>H and F is obtained by replacing all occurrences of G in E by H. Let the rule by which G=>H be LHS=>RHS, and let G=g(α,t1,..,tm), m>=0,

and each ti a labeled term. Take any two labels β and ξ in F. There are four cases.

Case 1. β and ξ are both in E. Since E is proper, these labels are not proper initial segments of each other.

Case 2. Only β is in E. Then, by the nature of LDF* rules, ξ=α*δ for some label δ in RHS. Since E is proper, β and α are not proper initial segments of each other. If β≠α then β and α*δ are also not proper initial segments of each other.

Suppose β=α. Since β occurs in E, E has a subterm f(β,s1,..,sn), n>=0. Since E is proper, f(β,s1,..,sn)=G. But since all occurrences of G are replaced by H, β cannot occur in F, as assumed. Hence this subsubcase cannot arise.

Case 3. Only ξ is in E. Same as case 2.

Case 4. None of β and ξ is in E. Then, by definition of LDF* rules, β=α*δ and ξ=α*ε, for some labels δ and ε in RHS. Since δ and ε are not proper initial segments of each other, neither are β and ξ. **QED.**

Lemma 9. Let P be an LDF* program. Let E be a proper term and let E reduce to F in an NA-step. Let A and B be two subterms of F such that the outermost label of A and of B is β. Then, A=B.

Proof. Let select(E,G). Then G=>H and F is obtained by replacing all occurrences of G in E by H. Let the rule by which G=>H be LHS=>RHS, and let the outermost label of G be α. There are four cases.

Case 1. A, but not B, is a subterm of H. Let the label of A, and of B be β. Since B is not a subterm of H, there occurs B1 in E, with label β, such that B is the result of replacing all occurrences of G in B1 by H.

Since A is a subterm of H, β occurs in H. However, β≠α*δ since α, and β both occur in E, and E is proper. Hence, β occurs in G. But then, since E is proper, B cannot properly contain G. Hence B1=B, so B occurs in E.

Now β is also the label of A, β≠α*δ, and A occurs in H. Hence A occurs in G, and so in E. Since E is proper, A=B, as required.

Case 2. B, but not A, is a subterm of H. Then, as in the previous case, B occurs in E. Hence A=B.

Case 3. Both A and B are subterms of H. Then A and B are also contained in G. Suppose A is not, but B is. Then, $\beta=\alpha*\delta$. Since B occurs in G, β also occurs in E. Contradiction with E is proper. Similarly, for A in G, but not B. Suppose none of A and B are in G. Without loss of generality assume A and B occur at distinct positions. Then, there must be distinct labels ϵ and ϕ in RHS such that $\beta=\alpha*\epsilon$ and $\beta=\alpha*\phi$. But this implies $\epsilon=\phi$ which, by the nature of labeled rules, is impossible. Hence both A and B are contained in G, and hence in E. Since E is proper, A=B.

Case 4. None of A and B is a subterm of H. Hence, there exist terms A1 and B1 in E such that A is obtained by replacing all occurrences of G in A1 by H and B is obtained from B1 similarly. Since A≠H, B≠H, the outermost label of A1 and B1 is also β. Since E is proper A1=B1. Hence A=B. **QED.**

Lemma 10. Let P be an LDF* program. Let a proper term E reduce to F in an NA-step. Then F is a proper term.

Proof. By Lemmas 8 and 9, F is a proper term. **QED.**

Lemma 11. Let P be an LDF* program. Let E0 be a proper term. Let E0,E1,..,Ek be an NA-derivation. Then, in this reduction, an FL-pair is eliminated at most once.

Proof. By induction on length k of E0,E1,..,Ek. If k=0, then clear. Otherwise, assume the theorem for E1,..,Ek. Let select(E0,G), G=>H and let E1 be obtained by replacing all occurrences of G in E0 by H. Let the outermost function symbol of G be f and its outermost label be α. Hence, $\langle f,\alpha\rangle$ is the pair eliminated in the reduction E0,E1.

If we can show that there is no term $f(\alpha,t1,..,tm)$ in E1,..,Ek, then, by induction hypothesis, we can conclude that no FL-pair is eliminated more than once in E0,E1,..,Ek. To show this, it is sufficient to show that the label α never occurs in E1,..,Ek. Since E0 is proper, and $\langle f,\alpha\rangle$ is eliminated, α does not occur in E1. Let ξ be a label in E2,..,Ek. Then, either $\xi=\beta$ for some label β in E1 in which case $\xi\neq\alpha$. Otherwise, $\xi=\beta*\epsilon$ for some label β in E1 and label ϵ. We show that it is not possible that $\beta*\epsilon=\alpha$.

Case 1. β occurs in E0. Since E0 is proper, β is not a proper initial segment of α. Hence, it is not possible that $\beta*\epsilon=\alpha$.

Case 2. β does not occur in E0. Then, by the nature of LDF* rules, $\beta=\alpha*\delta$, for some label δ. Hence, $\beta*\epsilon$ is longer than α, and so $\beta*\epsilon\neq\alpha$. **QED.**

Theorem 2. Minimality of LDF*. Let P be an LDF* program. Let E0 be a proper term. Let E0,E1,..,Ek be a successful reduction. Then there exists a successful leftmost NA-

derivation E0,F1,..,Fm such that m=<k.

Proof. Since E0,E1,..,Ek is a successful reduction, by reduction-completeness for F*,
Theorem 2, Section II, there exists a successful N-reduction E0,G1,..,Gn. Let the E-set of
E0,E1,..,Ek be S1 and that of E0,G1,..,Gn be S2. Then, by Lemma 6, S2 is a subset of
S1. By directionality of DF*, there exists a successful leftmost N-reduction E0,H1,..,Hn.
By Lemma 7, its E-set is also S2.

By Theorem 1 above, there exists a successful leftmost NA-derivation E0,F1,..,Fm whose
E-set, S3, is a subset of S2. Hence S3 is a subset of S1. By Lemma 11, the size of S3 is
m. The size of S1 is a lower bound on the number of steps in E0,E1,..,Ek. Hence m=<k.
QED.

IV.4 EXTENSION OF MINIMALITY RESULT TO NORMAL FORMS

We have shown that leftmost NA-derivations reduce proper terms to simplified forms in a
minimum number of steps. It appears to be straightforward to extend this result to normal
forms.

E reduces to F in an NAR-step if select-r(E,p), p=>q and F is the result of replacing each
occurrence of p in E by q. Definitions of NAR-derivations and leftmost NAR-derivations
are the obvious ones. The proof that leftmost NAR-reductions reduce proper terms to
normal forms in a minimum number of steps appears to be very similar to the above
proof.

IV.5 DERIVED MINIMALITY OF DF*

Lemma 12. Let P be a DF* program and E0 a term, where both P and E0 are ordinary.
Let P* and E0* be, respectively, their labeled versions. Let $E0\text{-}_p\text{>}E1$. Then there exists
E1* such that $E0^*\text{-}_{p*}\text{>}E1^*$ and E1* is a labeled version of E1.

Proof. There exist G,H such that E1=E0[G/H]. Proceed by induction on length of E0. If
E0 is a 0-ary function symbol g, then clear.

Otherwise, E0=f(t1,...,tm), m>0. Then E0*=f*(α,t1*,...,tm*) where Σ(f)=f* and for each i,
0=<i=<m, ti* is a labeled version of ti. Assume lemma for each of t1,...,tm.

Suppose G occurs in some ti in t1,..,tm, di=ti[G/H] and E1=f(t1,..,ti-1,di,ti+1,..,tm). Then,
by induction hypothesis, there exists di* such that ti*->di* and di* is a labeled version of
di. Let E1*=f*(α,t1*,..,ti-1*,di*,ti+1*,..,tm*). Clearly, E1* is a labeled version of E1.

Suppose G=E0. Then there is a rule f(L1,..,Lm)=>RHS such that E0 matches f(L1,..,Lm) with some substitution Φ and H=RHSΦ. Let a labeled version of this rule be f*(L,L1*,..,Lm*)=>RHS*. It is easily verified that E0* matches the head of this rule with substitution Φ* such that <L,α> is in Φ* and for each pair <X,t> in Φ, the pair <X,t*> is in Φ* where t* is a labeled version of t. It is also easily verified that RHS*Φ* is a labeled version of RHSΦ. **QED.**

Theorem 3. Derived minimality for DF*. Let P be a DF* program and E0 a term, where both P and E0 are ordinary. Let P* and E0* be, respectively, their labeled versions such that E0* is proper. Let E0,E1,..,Ek be a successful reduction in P. Then there exists a successful NA-derivation E0*,F1*,..,Fp* in P* such that p=<k.

Proof. We can ensure that E0* is a labeled version of E0 which is proper, simply by choosing distinct maximal labels for function symbols of E0. By Lemma 12, there exists a successful reduction E0*,E1*,..,Ek* such that for each i, Ei* is a labeled version of Ei. Since P* is an LDF* program, and E0* is proper, by Theorem 2, there exists a successful NA-derivation E0*,F1*,..,Fp* such that p=<k. **QED.**

V. COMPILATION OF F* INTO HORN CLAUSES

V.1 INTRODUCTION

A very simple algorithm is described, which compiles F* programs into Horn clauses in such a way that when SLD-resolution interprets them, it directly simulates the behavior of select. This is accomplished by compiling each F* rule into a distinct Horn clause, and combining in that clause, information about the logic of the rule, and information about the control of select when interpreting that rule. Thus, a specialized interpreter is produced for each rule.

If the F* program satisfies restriction (g) in Section III.2, the clauses resulting from its translation can be transformed to eliminate all redundant backtracking. If the program also satisfies restriction (f), i.e. is in DF*, SLD-search trees automatically contain exactly one branch. All the time, however, only *pure* clauses are produced.

The nature of logical variables is utilized to implement the assumption necessary for minimality. This is that when a term is reduced, all copies of it are simultaneously reduced. A logical variable has the property that when one occurrence of it in a term is bound to some term, all occurrences of it are simultaneously bound to the same term. Unfortunately, use must now be made of a metalogical feature (var), and an extra logical feature (cut). This is the *only* impure aspect in the entire LOG(F) system. Consequently, SLD-resolution, augmented with these features, computes NA-reductions.

LOG(F) is defined to be a logic programming system augmented with an F* compiler, and the equality axiom X=X. A ready-made implementation of LOG(F) is obtained by implementing the F* compiler in Prolog and using Prolog in place of SLD-resolution. Due to its depth-first search strategy, Prolog may sometimes not be able to simplify terms, even though select would. *However, if P is in DF*, Prolog always simplifies terms whenever select does.*

In all of the following, except in Section V.6, Prolog clauses and Prolog are synonymous with Horn clauses and SLD-resolution. Only in Section V.6 do they refer to the *programming language*.

V.2 COMPILATION ALGORITHM

Let P be an F* program. The compilation of P into Prolog proceeds in two stages.

Stage 1. For each n-ary, n>=0, constructor symbol c in P, and where X1,..,Xn are distinct variables, generate the clause:

reduce(c(X1,..,Xn),c(X1,..,Xn))

Stage 2. Let f(L1,..,Lm)=>RHS be a rule in P where f is an m-ary, m>=0, non-constructor function symbol and each of RHS and L1,..,Lm is a term, possibly containing variables. For each such rule perform the following steps:

> **(a)** Let A1,..,Am be distinct Prolog variables none of which occur in the rule. If Li is a variable let Qi be Ai=Li. If Li is c(X1,..,Xn) where c is a constructor symbol, and each Xi a variable, let Qi be reduce(Ai,c(X1,..,Xn)).

> **(b)** Let Out be a Prolog variable not occurring in the rule, and different from A1,..,Am. Generate the predication reduce(RHS,Out).

> **(c)** Generate the clause:

> > reduce(f(A1,..,Am),Out):-Q1,..,Qm,reduce(RHS,Out).

For example the F* rules:

> append([],X)=>X
> append([U|V],W)=>[U|append(V,W)]
> intfrom(N)=>[N|intfrom(s(N))].
> if(true,X,Y)=>X.
> if(false,X,Y)=>Y.

are compiled into:

> reduce([],[]).
> reduce([U|V],[U|V]).
> reduce(true,true).
> reduce(false,false).

> reduce(append(A1,A2),Out):-reduce(A1,[]),A2=X,reduce(X,Out).
> reduce(append(A1,A2),Out):-
> > reduce(A1,[U|V]),A2=W,reduce([U|append(V,W)],Out).
> reduce(intfrom(N),Out):-reduce([N|intfrom(s(N))],Out).
> reduce(if(T,X,Y),Out):-reduce(T,true),reduce(X,Out).
> reduce(if(T,X,Y),Out):-reduce(T,false),reduce(Y,Out).

It can be seen that where reduce(f(A1,..,Am),Out):-Q1,..,Qm,reduce(RHS,Out) is the translation of f(L1,..,Lm)=>RHS, Q1,..,Qm represent the attempt to match some term

f(t1,..,tm) with f(L1,..,Lm). If these succeed, the match succeeds with some substitution α. Now, reduce(RHS,Out) represents simultaneously, application of α to RHS, and recursive simplification of RHSα. The correctness of compilation algorithm is formally proved in Section V.7.

In practice, in stage 2(a) if Li is a variable, then Ai in f(A1,..,Am) is replaced by Li, and Ai=Li is not generated. This eliminates a procedure call, and so yields substantially faster code. However, proofs of propositions below are easier to derive without this optimization.

V.3 COMPUTING AND PRINTING NORMAL FORMS

If there is a method to compute simplified forms of terms, it can be applied repeatedly to compute normal forms of terms. *This is guaranteed by reduction-completeness for normal forms, Theorem 4, Section II*. In particular, for each m-ary constructor symbol we can add the following rule:

nf(E,c(X1,..,Xm)):-reduce(E,c(T1,..,Tm)),nf(T1,X1),..,nf(Tm,Xm).

Now, to compute the normal form of a term E, we can execute nf(E,X), where X is a variable. The correctness of this rule for computing normal forms can easily be proved from the arguments of Section V.7.

Clearly, computing normal forms is only sensible when they are finite. If they are not, we can at least print finite portions of them as they are generated. For example, we can print members of an infinite list as follows:

print_list(X):-reduce(X,[U|V]),write(U),write(' '),print_list(V).

V.4 OPTIMIZING RULES SATISFYING RESTRICTION (g)

Let P be an F* program and PC its compiled version. Let f(t11,..,t1i,..,t1m)=>RHS1, .., f(tn1,..,tni,..,tnm)=>RHSn be the n rules defining f in P, and C1,..,Cn be, respectively, their compiled versions. Let the rules satisfy restriction (g), Section III.2. Then, if t1i is a variable, the ith literal in bodies of C1,..,Cn will be, respectively, Ai=t1i,..,Ai=tni, for some variable Ai. Otherwise, the ith literals in C1,..,Cn would be, respectively, reduce(Ai,t1i),..,reduce(Ai,tni).

If t1i is not a variable, the query reduce(f(a1,..,ai,..,am),Z) may, due to backtracking, cause evaluation of each of reduce(ai,t1i),..,reduce(ai,tni). We can ensure that reduce is called just once for ai by taking advantage of the fact that all reduce clauses have the

same form. That is, we can collapse them all into the single clause:

reduce(f(A1,..,Am),Z):-R1,..,Rm,f(X1,..,Xm)=>RHS,reduce(RHS,Z).

where X1,..,Xm are distinct variables not occurring in any of the clauses, and if t1i is a variable, Ri is Ai=Xi, otherwise Ri is reduce(Ai,Xi). Now reduce would be called just once for ai. Of course, the => rules now need to be included with the reduce clauses. Thus Prolog execution can be considerably speeded up.

Furthermore, if P is a DF* program then f(X1,..,Xm)=>RHS will succeed at most once. Hence, for any ground terms t1,..,tm, and variable Z, the search tree rooted at reduce(f(t1,..,tm),Z) will contain exactly one branch. *Thus, the reduce clauses would form a deterministic logic program.* For example, consider the DF* program:

append([],X)=>X.
append([U|V],W)=>[U|append(V,W)].

Its compiled version, excluding rules for constructor symbols, is:

reduce(append(A1,A2),Z):-reduce(A1,[]),A2=X,reduce(X,Z).
reduce(append(A1,A2),Z):-
          reduce(A1,[U|V]),A2=W,reduce([U|append(V,W)],Out).

These two rules can be collapsed into a single one:

reduce(append(A1,A2),Z):-
          reduce(A1,X1),A2=X2,append(X1,X2)=>RHS,reduce(RHS,Z).

Now, given the query reduce(append([1],[2]),Z), an attempt would be made to simplify [1] just once, and not twice, as with the original pair of reduce clauses. Also, since the append rules are in DF*, the SLD-search tree rooted at reduce(append([1],[2]),Z) contains exactly one branch.

V.5 COMPUTING FUNCTIONS EAGERLY IN F*

If a function is defined in F*, it is computed lazily. Often it is very desirable that some functions, such as arithmetic functions, be computed eagerly. We show one way to accomplish this.

A lazy function symbol is one which is defined in F*. An eager function symbol is one which is defined in Prolog. Only right hand sides of F* rules can contain calls to eager

functions. Let E be a subterm, possibly containing variables, of the right hand side of an F* rule. Let the outermost function symbol of E be eager. Then E must not contain any lazy function symbol. For example, where length is eager, and append is lazy, the term length(append([],[1])) must not appear in any F* rule.

Now, let LHS=>RHS be an F* rule, f an eager function, and f(t1,..,tn) a subterm, possibly containing variables, of RHS. Let f be defined by an n+1 ary predicate symbol p(A1,..,An,A), such that A1,..,An are input positions and A the output position. Let RHS1 be the result of replacing f(t1,..,tn) in RHS by X, where X is a variable not occurring in LHS=>RHS. Generate the condition p(t1,..,tn,X), and add it to the conditions generated in Stage 2 (a) of Section V.2. Of course, if t1,..,tn themselves involve calls to eager functions, they must be treated similarly. For example, let multiple be an eager function defined in Prolog as follows:

        multiple(A,B,true):-0 is A mod B.
        multiple(A,B,false):-not(0 is A mod B).

Now the rule:

        filter(A,[U|V])=>if(multiple(U,A),filter(A,V),[U|filter(A,V)]).

is compiled into:

        reduce(filter(A,X),Z):-
                reduce(X,[U|V]),
                multiple(U,A,T),
                reduce(if(T,filter(A,V),[U|filter(A,V)]),Z).

However, some care still needs to be exercised. For example, where zerop and / are eager functions, defined in Prolog by, respectively, zerop and div, the rule:

        f(X)=>if(zerop(X),[X],[1/X]).

will be compiled into:

        reduce(f(X),Z):-zerop(X,T),div(1,X,A),reduce(if(T,[X],[A]),Z).

Now, if X is 0, the call to div will cause an unintended division by 0. But one can rewrite the above rule as:

        f(X)=>if(zerop(X),[X],h(X)).

h(X)=>[1/X].

V.6 COMPILING LDF* PROGRAMS

We now show how to represent labeled terms in Prolog, and compile LDF* programs into Prolog in such a way that NA-steps can be performed efficiently. The main idea is that labels can be represented by logical variables. These have the property that if one occurrence of a variable in term E is bound to term F, all occurrences of the variable in E are simultaneously bound to F.

Let E be a proper term and let E reduce to F in an NA-step. Then there is a subterm G of E such that G=>H, and F is obtained by replacing all occurrences of G in E by H. Note that each of G,H,F is proper. Let E contain the labels $\alpha 1,..,\alpha n$. Let $V1,...,Vn$ be distinct variables and E* the result of replacing for each i, all occurrences of αi in E by Vi. Then E* is a Prolog representation of E. Similarly, let G*,H*,F* be Prolog representations of G,H,F respectively such that H* and E* do not have any variables in common. Then G*=f(V,t1,..,tm) where V is a variable. If we now bind V to H*, all occurrences of V in E* are bound to H*. Let the result be F1*.

Now, before attempting to match a term with a non-variable term, we take the precaution of checking whether its label is already bound to some term. If so, we attempt to match this term with the non-variable term. Otherwise, we proceed as usual. Thus, after V has been bound to H*, if another occurrence of G* is to be matched with some term, we attempt to match H* with it.

At a later stage it is possible that the label of H* itself be bound to a term. Thus, before matching a term, it may be necessary to "dereference" its label a number of times. It is not unreasonable to assume that the cost of dereferencing is small compared to that of reduction. Thus, we can work with F1* instead of F*, so replacement of all occurrences of a term is implemented efficiently. Moreover, F* can be obtained from F1* by dereferencing. The algorithm for compiling LDF* programs can be found in [Narain 1988]. In practice, DF* programs can be compiled directly into reduce clauses with labels, without first transforming them into LDF* programs. The appropriate algorithm can easily be worked out.

It will be recognized that our scheme for implementing NA-derivations is exactly the graph-reduction scheme with indirection nodes described in [Turner 1979] and [O'Donnell 1982]. *However, in our case it is possible to ensure that the length of the dereferencing chain is exactly one.* Details can be obtained in [Narain 1988]. For example, where nil is a zero-ary constructor symbol, let P be the following DF* program:

```
merge(nil,nil)=>nil.
double(X)=>merge(X,X).
h=>d.
```

This is compiled into:

(1) reduce(merge(V,A1,A2),Z):-not var(V),reduce(V,Z),!.
(2) reduce(double(V,A1),Z):-not var(V),reduce(V,Z),!.
(3) reduce(h(V),Z):-not var(V),reduce(V,Z),!.

(4) reduce(nil(N),nil(N)).
(5) reduce(merge(Z,A1,A2),Z):-
        reduce(A1,nil(N1)),reduce(A2,nil(N2)),reduce(nil(N3),Z).
(6) reduce(double(Z,A1),Z):-reduce(merge(N,A1,A1),Z).
(7) reduce(h(Z),Z):-reduce(d(D),Z).

Consider the query reduce(double(A,h(B)),Z), which has as descendant
reduce(merge(N,h(B),h(B)),Z). Suppose the first call, reduce(h(B),nil(N1)), in (5)
succeeds, but only after a long and complicated deduction. Then B is bound to nil(N1).
Now, due to (3), the second call, reduce(h(B),nil(N2)), in (5) will terminate in just three
inference steps. The cut (!) will prevent (7) from being tried all over again. Also note
that of these three inference steps, only one is a dereferencing step. The number of these
steps is constant, regardless of the function definitions.

V.7 CORRECTNESS OF F* COMPILATION ALGORITHM

Lemma 1. Let P be an F* program. If:

(1) E0=f(t1,..,ti,..,tm), and
(2) Ek=f(s1,..,si,..,sm), and
(3) si is simplified, and
(4) E0,..,Ek, k>=0, is an N-reduction such that for no i, Ei=>Ei+1.

Then there is a successful N-reduction ti,..,si of length less than or equal to the length k of
E0,E1,..,Ek.

Proof: By Lemma 8, Section III. **QED.**

Lemma 2. Let P be an F* program, and PC its compiled version. Let A be a ground term
and B a term, possibly containing variables, such that reduce(A,B) succeeds, in the sense
of SLD-resolution, with answer substitution σ. Then Bσ is ground.

Proof: By induction on length n of successful SLD-derivation reduce(A,B),G1,..,Gn=□.
QED.

Lemma 3. Let P be an F* program and PC its compiled version. Let A and B be ground
terms such that reduce(A,B) succeeds. Let D be a term, possibly containing variables,
such that for some substitution α, Dα=B. Then reduce(A,D) succeeds with answer
substitution α.

Proof: By induction on length n of successful SLD-derivation starting at reduce(A,B).
QED.

Lemma 4. Let P be an F* program. Let PC be the compiled version of P. Let E0,..,En be
a successful N-reduction. Then reduce(E0,En) succeeds in the presence of PC.

Plan of Proof: By induction on length of successful N-reduction E0,..,En. We show that
there is some Ej, j>0, in E0,..,En such that an SLD-derivation of reduce(E0,En) contains
the goal reduce(Ej,En). Since Ej,..,En is also a successful N-reduction, by induction
hypothesis, reduce(Ej,En) succeeds. Hence reduce(E0,En) succeeds.

Proof: By induction on length n of successful reduction E0,..,En. If n=0 then E0 is
already simplified. In particular, E0=c(t1,..,tm) where c is an m-ary constructor symbol,
m>=0, and t1,..,tm are terms. There is a clause in PC reduce(c(X1,..,Xm),c(X1,..,Xm))
where each Xi is a variable. Clearly reduce(E0,E0) succeeds.

Let n>0 and E0=f(t1,..,tm), f not a constructor symbol, each ti a term and m>=0. Assume
theorem holds for all successful reductions of length less than n.

Since E0 is not simplified, the N-reduction is of the form E0,..,Ek-1,Ek,..,En, 0<k=<n,
such that Ek-1=>Ek, but for no i, 0=<i<k-1, Ei=>Ei+1. Hence, Ek-1=f(s1,..,sm) for some
terms s1,..,sm. Since Ek-1=>Ek, there is some rule f(L1,..,Lm)=>RHS such that Ek-1
matches f(L1,..,Lm) with some substitution σ and Ek=RHSσ. Since L1,..,Lm do not share
any variables, σ is the union of σ1,..,σm such that for each Li in L1,..,Lm, si matches Li
with substitution σi.

For each i, if Li is not a variable, then since si matches Li, si is in simplified form. For
such i, there is, by Lemma 1, a successful N-reduction ti,..,si of length less than or equal
to k-1.

The rule f(L1,..,Lm)=>RHS is compiled into the Horn clause

       reduce(f(X1,..,Xm),Z):- Q∪{reduce(RHS,Z)}

in accordance with the compilation rules stated above. This clause is contained in PC.

Consider the query reduce(E0,En), i.e. reduce(f(t1,..,tm),En). It unifies with reduce(f(X1,..,Xm),En) with m.g.u. τ={<X1,t1>,...,<Xm,tm>,<Z,En>} and its immediate descendant is (Q$\cup${reduce(RHS,Z)})τ. Since RHS does not contain any of the Xi, this is Q$\tau\cup${reduce(RHS,En)}.

Let Q1,..,Qm be the members of Q. Consider some Qi. If Qi is Xi=Li, then Qiτ=(ti=Li) which succeeds with answer substitution {<Li,ti>}. Of course, ti matches Li, so {<Li,ti>}=σi.

Otherwise, Qi=reduce(Xi,Li), so Qiτ=reduce(ti,Li). Since there is a successful N-reduction ti,..,si of length less than or equal to k-1, by induction hypothesis, reduce(ti,si) succeeds. Since Liσi=si, by Lemma 3, reduce(ti,Li) also succeeds with answer substitution σi.

By repeating the same argument for each Qi, we see that an SLD-derivation starting at reduce(E0,En) contains reduce(RHSσ1,..,σm,En) as a member. Since σ is the union of σ1,..,σm and no variable is defined in more than one σi in σ1,..,σm, RHSσ1,..,σm=RHSσ. But RHSσ=Ek. Hence the SLD-derivation starting at reduce(E0,En) contains reduce(Ek,En). Since the length of the successful reduction Ek,..,En is less than n, by induction hypothesis, reduce(Ek,En) succeeds. Thus, the query reduce(E0,En) succeeds. **QED.**

Lemma 5. Let P be an F* program. Let PC be the compiled version of P. Let E0 and En be terms such that reduce(E0,En) succeeds in the presence of PC. Then there is a successful N-reduction E0,..,En.

Plan of Proof: By induction on length of successful SLD-derivation reduce(E0,En),..,□. We show that there is some goal reduce(Ej,En), j>0, in this derivation such that there is an N-reduction E0,..,Ej. Since reduce(Ej,En) succeeds, by induction hypothesis, there is a successful N-reduction Ej,..,En. So there is a successful N-reduction E0,..,Ej,..,En.

Proof: By induction on length n of successful SLD-derivation starting at reduce(E0,En). If n=1 then there is a clause reduce(c(X1,..,Xm),c(X1,..,Xm)) in PC such that reduce(E0,En) unifies with the head of this clause. Clearly, then, E0=En, En is simplified and the required N-reduction is simply E0.

Let n>0. Assume lemma for all successful derivations of length less than n. Assume E0=f(t1,..,tm) for some non-constructor function symbol f and terms t1,..,tm. Since reduce(E0,En) succeeds there is a clause in PC:

reduce(f(X1,..,Xm),Z):-Q∪{reduce(RHS,Z)}

such that it is the compilation of a rule f(L1,..,Lm)=>RHS in P. Moreover, reduce(f(t1,..,tm),En) unifies with the head of the above clause with m.g.u. τ={<X1,t1>,..,<Xm,tm>,<Z,En>} and Qτ U {reduce(RHS,Z)}τ has a successful derivation of length n-1. Also, RHSτ=RHS and Zτ=En.

If Q is empty, m=0. So, by restriction (e) RHS is ground. By induction hypothesis there is a successful N-reduction RHS,..,En. E0 matches f(L1,..,Lm) and so E0=>RHS. Hence E0,RHS,..,En is a successful N-reduction.

Suppose Q is non-empty. Let Q1,..,Qm be the members of Q. Consider Qi. If Qi=(Xi=Li) then ti unifies with Li with substitution σi={<Li,ti>}. Construct the singleton sequence f(t1,..,ti,..,tm). This sequence is an N-reduction.

If Qi=reduce(Xi,Li) then Li=c(U1,..,Uk) for some constructor symbol c and variables U1,..,Uk. Also Qiτ=reduce(ti,Li). Clearly, reduce(ti,Li) succeeds. Let the answer substitution be σi. By Lemma 2, Liσi is ground. Then reduce(ti,Liσi) also succeeds. The successful derivation of reduce(ti,Liσi) is the same as that of reduce(ti,Li) with Li replaced by Liσi. So, the length of this derivation is also less than n. By induction hypothesis, there is a successful N-reduction ti,..,Liσi. By Lemma 4 of Section II, the sequence f(t1,..,ti,..,tm),..,f(t1,..,Liσi,..,tm) is an N-reduction.

Hence we obtain the N-reductions f(t1,..,tm),..,f(L1σ1,..,tm) and f(L1σ1,t2,..,tm),..,f(L1σ1,L2σ2,..,sm) and .. f(L1σ1,L2σ2,..,tm),..,f(L1σ1,L2σ2,..,Lmσm). The concatenation of these reductions is itself an N-reduction. Since L1,..,Lm do not share variables, f(L1σ1,..,Lmσm) matches f(L1,..,Lm) with a substitution which is the union of σ1,..,σm. Let σ be this union. Hence f(L1σ1,..,Lmσm)=>RHSσ. Since all the variables of RHS are in L1,..,Lm and for each σi, Liσi is ground, RHSσ is ground.

The predication reduce(RHSσ,En) succeeds and the length of the associated successful derivation is less than n. By induction hypothesis, there is a successful N-reduction RHSσ,..,En. Hence there is a successful N-reduction f(t1,..,tn),..,f(L1σ1,..,Lmσm),RHSσ,..,En. **QED.**

Theorem 1. The correctness of the compilation of F*. Let P be an F* program and PC be its compilation. Let E0 and En be ground terms. Then there is a successful N-reduction beginning with E0 and ending with En iff PC⊢reduce(E0,En).

Proof: Lemmas 4 and 5 state, respectively, the if and only if parts of the theorem. **QED.**

VI. PROGRAMMING IN LOG(F)

VI.1 INTRODUCTION

This section describes seven examples of programming in LOG(F). The first illustrates non-determinism of LOG(F), and usefulness of lazy evaluation even when manipulating finite data structures. The second shows how useful cases of the rule of substitution of equals for equals can be implemented. The third obtains a new proof of confluence of combinatory logic. The fourth shows how a pair of communicating processes can be simulated. The fifth illustrates the power of NA-derivations, and manipulation of infinite numerical structures. The sixth illustrates manipulation of infinite graphical structures. The seventh compares LOG(F) with the system of Tamaki [1984]. In each case, clauses listed are those obtained after performing optimizations discussed in previous sections. Finally, Section VI.9 compares performance of LOG(F) with that of Prolog.

VI.2 NON-DETERMINISM IN F*

As discussed in Section I, permutations of lists can be computed by the following F* program:

```
perm([])=>[].
perm([U|V])=>insert(U,perm(V)).
insert(U,X)=>[U|X].
insert(U,[A|B])=>[A|insert(U,B)].
```

This is compiled, and optimized into:

```
reduce([],[]).
reduce([A|B],[A|B]).

reduce(insert(A,B),[A|B]).
reduce(insert(A,B),[C|insert(A,D)]):-reduce(B,[C|D]).
reduce(perm(A),B):-reduce(A,C),perm(C)=>D,reduce(D,B).

perm([])=>[].
perm([A|B])=>insert(A,perm(B)).
```

Note that some => rules survive in the compiled version. This is due to the method, discussed in Section V.4, of compiling F* programs satisfying restriction (g). If we now type reduce(perm([1,2,3]),Z), we obtain Z=[1|perm([2,3])], Z=[2|insert(1,perm([3]))], Z=[3|insert(1,insert(2,perm([])))]. However, if we define:

```
make_list(X,[]):-reduce(X,[]).
make_list(X,[U|V]):-reduce(X,[U|B]),make_list(B,V).
```

and then type make_list(perm([1,2,3]),Z), we obtain Z=[1,2,3],..,Z=[3,2,1].

The above program can be used to implement a very efficient solution to the N-queens
problem which is to place N queens on an NxN chess board so that no two queens attack
each other. It is easily seen that each queen must be in a distinct row and column, so that
candidates for solutions can be represented by permutations of the list [1,2,..,N]. The
position of the ith queen in a permutation p is [i,q] where q is is the ith element of q. The
problem now reduces to generating all permutations of [1,2,..,N] and testing whether they
are safe, or represent a solution.

Lazy evaluation guarantees that permutations are tested as soon as they are generated. If
it is determined that [A1,..,Am], m=<N is unsafe then no permutation with [A1,..,Am] as
initial segment is generated. This yields a drastic pruning of the search space. The
program is:

```
if(true,X,Y)=>X.
if(false,X,Y)=>Y.
queens(X)=>safe(perm(X)).
safe([])=>[].
safe([U|V])=>[U|safe(nodiagonal(U,V,1))].
nodiagonal(U,[],N)=>[].
nodiagonal(U,[A|B],N)=>if(noattack(U,A,N),[A|nodiagonal(U,B,N+1)],none).
noattack(U,A,N)=>neg(equal(abs(U-A),N)).
```

This is compiled into:

```
reduce([],[]).
reduce([U|V],[U|V]).
reduce(true,true).
reduce(false,false).

reduce(queens(A),B):-queens(A)=>C,reduce(C,B).
reduce(safe(A),B):-reduce(A,C),safe(C)=>D,reduce(D,B).
reduce(if(A,B,C),D):-reduce(A,E),if(E,B,C)=>F,reduce(F,D).
reduce(noattack(A,B,C),D):-noattack(A,B,C)=>E,reduce(E,D).
reduce(nodiagonal(A,B,C),D):-reduce(B,E),nodiagonal(A,E,C)=>F,reduce(F,D).

queens(A)=>safe(perm(A)).
```

```
safe([])=>[].
safe([A|B])=>[A|safe(nodiagonal(A,B,1))].
if(true,A,B)=>A.
if(false,A,B)=>B.
nodiagonal(A,[],B)=>[].
nodiagonal(A,[B|C],D)=>
        if(noattack(A,B,D),[B|nodiagonal(A,C,E)],none):-E is D+1.
noattack(A,B,C)=>D:-E is A-B,abs(E,F),equal(F,C,G),neg(G,D).
```

The eager functions are defined in Prolog:

```
abs(X,X):-X>=0.
abs(X,Y):-X<0,Y is -X.
neg(true,false).
neg(false,true).
equal(A,A,true).
equal(A,B,false):-not A=B.
less_than(U,A,true):-U<A.
less_than(U,A,false):-U>=A.
```

If we now type make_list(queens([1,2,3,4]),Z), we obtain Z=[2,4,1,3] and Z=[3,1,4,2].

VI.3 IMPLEMENTING SUBSTITUTION OF EQUALS FOR EQUALS

If a DF* program is interpreted as an equality theory, reduce clauses can be thought of as implementing an equality theory in Prolog with the restriction that it be used only for simplification of terms. Now, given a clause of the form p(c(X1,..,Xm)):-Body, where c is a constructor symbol, we can add another clause stating a rule of substitution of equals:

```
p(X):-reduce(X,c(X1,..,Xm)),p(c(X1,..,Xm)).
```

Now, even when a term E is not of the form c(X1,..,Xm), p can still be inferred for E, provided E is reducible to a term of the form c(X1,..,Xm). For example, from:

```
married(X):-spouse(X,Y).
spouse(scott,a).
```

one can infer married(scott). One can now add the clause:

```
married(X):-reduce(X,Y),married(Y).
```

An equality theory is:

    author(waverley)=>author(ivanhoe).
    author(ivanhoe)=>scott.

The reduce clauses for the last two => rules are:

    reduce(scott,scott).
    reduce(ivanhoe,ivanhoe).
    reduce(waverley,waverley).

    reduce(author(X),Z):-reduce(X,waverley),reduce(author(ivanhoe),Z).
    reduce(author(X),Z):-reduce(X,ivanhoe),reduce(scott,Z).

Here scott, waverley, and ivanhoe are constructor symbols. Now one can infer, in Prolog, married(author(waverley)), i.e. the result of substituting author(waverley) for scott in married(scott).

VI.4 COMBINATORY LOGIC

A new proof is obtained of the theorem that the SKI calculus is confluent. Following the ideas of Ait-Kaci & Nasr [1986], SKI reduction rules can be expressed as a DF* program:

    apply(k,X)=>k1.
    apply(k1(X),Y)=>X.
    apply(s,F)=>s1(F).
    apply(s1(F),G)=>s2(F,G).
    apply(s2(F,G),X)=>apply(apply(F,X),apply(G,X)).

Here k,s,k1,s1,s2 are constructor symbols, and apply a non-constructor symbol. From confluence of DF*, it follows that the SKI calculus is also confluent. These rules are translated into the following reduce clauses:

    reduce(s,s).
    reduce(k,k).
    reduce(k1(X),k1(X)).
    reduce(s1(X),s1(X)).
    reduce(s2(X,Y),s2(X,Y)).

    reduce(apply(A,B),Z):-reduce(A,k),reduce(k1(B),Z).

```
reduce(apply(A,B),Z):-reduce(A,k1(D)),reduce(D,Z).
reduce(apply(A,B),Z):-reduce(A,s),reduce(s1(B),Z).
reduce(apply(A,B),Z):-reduce(A,s1(C)),reduce(s2(C,B),Z).
reduce(apply(A,B),Z):-
         reduce(A,s2(D,E)),reduce(apply(apply(D,B),apply(E,B)),Z).
```

These clauses can be used to contemplate higher-order programming in LOG(F).

VI.5 TWO WAY COMMUNICATION

This example models communcation between two users, each of whom types a stream of tokens on his screen. Each token is of the form [A] or [send,M] in which case M appears on both screens. The communication is modeled by:

```
extract_messages([[A]IX])=>extract_messages(X).
extract_messages([[send,M]IX])=>[Mlextract_messages(X)].


screen1=>fair_merge(key1,extract_messages(key2)).
screen2=>fair_merge(key2,extract_messages(key1)).
```

Here send, [] and I are constructor symbols. We assume there exists a function fair_merge which takes as input two streams and interleaves their tokens into an output stream. If two tokens appear in some order in an input, then they appear in the same order in the output. Finally, fair_merge consumes each input at the rate at which it is produced.

Note that the second extract_messages rule has a left hand side of depth greater than two, so, strictly speaking, it is not an F* rule. However, it can be expressed in F* as follows:

```
extract_messages([AIX])=>g(A,X).
g([UIV],X)=>h(U,V,X).
h(send,V,X)=>[Vlextract_messages(X)].
```

Here g and h are auxiliary function symbols. Assuming that key1 and key2 are streams of tokens typed by, respectively, the first and second user, the term screen1 will reduce to the stream of tokens appearing on the first user's screen. Similarly for screen2. The reduce clauses are:

```
reduce([],[]).
reduce([UIV],[UIV]).
reduce(send,send).
```

```
reduce(extract_messages(A),B):-
        reduce(A,[C|D]),reduce(C,[E]),reduce(extract_messages(D),B).
reduce(extract_messages(A),[B|extract_messages(C)]):-
        reduce(A,[D|C]), reduce(D,[E|F]), reduce(E,send), reduce(F,[B]).
reduce(screen1,A):-reduce(fair_merge(key1,extract_messages(key2)),A).
reduce(screen2,A):-reduce(fair_merge(key2,extract_messages(key1)),A).
```

VI.6 HAMMING'S PROBLEM

The problem, described in [Dijkstra 1976], is to generate, in increasing order, all those
numbers which are divisible by no primes other than 2,3 or 5. Dijkstra states that an
equivalent problem is to generate the sequence of numbers, in ascending order, defined
by the following axioms:

(a) 1 is in the sequence
(b) If x is in the sequence, then so are 2*x, 3*x and 5*x.
(c) The sequence contains no values except those on account of (a) and (b).

These axioms can be expressed by the following DF* program:

```
hamming=>hamming_aux([1|hamming]).
hamming_aux(X)=>
        merge(times_list(2,X),merge(times_list(3,X),times_list(5,X))).


merge([U|V],[A|B])=>if(U<A,[U|merge(V,[A|B])],merge_aux(U,V,A,B)).
merge_aux(U,V,A,B)=>if(equal(U,A),[U|merge(V,B)],[A|merge([U|V],B)]).


times_list(N,[])=>[].
times_list(N,[U|V])=>[U*N|times_list(N,V)].
```

Function times_list multiplies each element of its input list by a fixed number. Function
merge takes two lists in ascending order and merges their elements in increasing order.
Functions hamming and hamming_aux are implementations of axioms (a),(b),(c).

This program illustrates the power of NA-derivations. The definition of hamming_aux
contains three occurrences of X on the right hand side. If care is taken that whenever the
term at one occurrence of X is reduced, terms at the other two occurrences of X are also
reduced, the list hamming is produced with little overhead. If not, then the overhead
increases exponentially. This can be felt by comparing the speed with which elements of
hamming are printed on the screen in the two cases. The labeled version of this program
is compiled into the following reduce clauses:

reduce(hamming(A),B):-not var(A),B=A,!.
reduce(hamming_aux(A,B),C):-not var(A),C=A,!.
reduce(merge(A,B,C),D):-not var(A),D=A,!.
reduce(merge_aux(A,B,C,D,E),F):-not var(A),F=A,!.
reduce(times_list(A,B,C),D):-not var(A),D=A,!.
reduce(if(A,B,C,D),E):-not var(A),E=A,!.

reduce([],[]).
reduce([A|B],[A|B]).
reduce(true,true).
reduce(false,false).

reduce(hamming(A),A):-hamming(B)=>C,reduce(C,A).
reduce(hamming_aux(A,B),A):-hamming_aux(C,B)=>D,reduce(D,A).
reduce(merge(A,B,C),A):-
        reduce(B,D),reduce(C,E),merge(F,D,E)=>G,reduce(G,A).
reduce(merge_aux(A,B,C,D,E),A):-merge_aux(F,B,C,D,E)=>G,reduce(G,A).
reduce(times_list(A,B,C),A):-reduce(C,D),times_list(E,B,D)=>F,reduce(F,A).
reduce(if(A,B,C,D),A):-reduce(B,E),if(F,E,C,D)=>G,reduce(G,A).

hamming(A)=>[1|hamming_aux(B,hamming(C))].
hamming_aux(A,B)=>
        merge(C,times_list(D,2,B),
                merge(E,times_list(F,3,B),times_list(G,5,B))).
merge(A,[B|C],[D|E])=>
        if(F,G,[B|merge(H,C,[D|E])],merge_aux(I,B,C,D,E)):-less_than(B,D,G).
merge_aux(A,B,C,D,E)=>
        if(F,G,[B|merge(H,C,E)],[D|merge(I,[B|C],E)]):-equal(B,D,G).
times_list(A,B,[])=>[].
times_list(A,B,[C|D])=>[E|times_list(F,B,D)]:-E is C*B.
if(A,true,B,C)=>B.
if(A,false,B,C)=>C.

Definitions of the eager functions less_than and equal are as in Section VI.2. If we now
type print_list(hamming(_)), we obtain 1,2,3,4,5,6,8,9,10,12,...

VI.7 INFINITE GRAPHICAL STRUCTURES.

Henderson [1982] has shown how to use functional programming for defining and
manipulating graphical structures. In particular, he shows how to construct Square Limit,
an Escher woodcut. We use Henderson's building blocks to tile the x-y plane in an

VI-8 Programming in LOG(F)

interesting way. A picture is represented by a list of vectors, each of the form v(A,B)--
v(X,Y), where A,B,X,Y are real numbers. Transformations on pictures, such as
composition, translation, scaling, or rotation (about the origin) are defined as follows:

```
union([],X)=>X.
union([FX|RX],Y)=>[FX|union(Y,RX)].

rotate([],_)=>[].
rotate([v(X,Y)--v(A,B)|L],Theta)=>
 [v(X*cos(Theta)-Y*sin(Theta),X*sin(Theta)+Y*cos(Theta))--
 v(A*cos(Theta)-B*sin(Theta),A*sin(Theta)+B*cos(Theta))|rotate(L,Theta)].

translate([],_,_)=>[].
translate([v(X,Y)--v(A,B)|L],Dx,Dy)=>
        [v(X+Dx,Y+Dy)--v(A+Dx,B+Dy)|translate(L,Dx,Dy)].
scale([],_,_)=>[].
scale([v(X,Y)--v(A,B)|L],Kx,Ky)=>
        [v(X*Kx,Y*Ky)--v(A*Kx,B*Ky)|scale(L,Kx,Ky)].
```

The basic pictures are p,q,r,s, drawn in a 36x36 grid, and shown in order in the top row in
Figure 1. (The vectors can be found, not unfortunately, in Henderson's paper, but in
[Robinson & Green 1987]). These are combined by quartet into t, shown in the second
row. The third and fourth rows show, respectively, block1(t) and block2(t), the two basic
144x72 rectangles. row(Block,0) repeats Block, infinitely often, at intervals of 144 units,
in the x and -x directions. alt_rows(Row,0) repeats a row infinitely often, at intervals of
144 units, in the y and -y directions. mosaic(Block1,Block2) computes rows of Block1
and Block2, alternates these, and then composes these to tile the x-y plane, Figure 2. The
program is:

```
rot_pos(X)=>translate(rotate(translate(X,-72,-72),-1.57),72,0).
rot_neg(X)=>translate(rotate(translate(X,-72,-72),1.57),0,72).

block1(X)=>union(X,translate(rot_neg(X),72,0)).
block2(X)=>
 union(rot_pos(X),
     translate(rotate(translate(rot_pos(X),-72,0),-1.57),72,0)).

row(Block,N)=>union(translate(Block,144*N,0),
                 union(translate(Block,-144*N,0),row(Block,N+1))).

alt_rows(Row,N)=>union(translate(Row,0,144*N),
```

union(translate(Row,0,-144*N),alt_rows(Row,N+1))).

mosaic(Block1,Block2)=>union(alt_rows(row(Block1,0),0),
                    translate(alt_rows(row(Block2,0),0),0,72)).
beside(A,B)=>union(A,translate(B,36,0)).
above(A,B)=>union(A,translate(B,0,36)).
quartet(P1,P2,P3,P4)=>above(beside(P3,P4),beside(P1,P2)).

t=>quartet(p,q,r,s).

p=>[..].
q=>[..].
r=>[..].
s=>[..].

Note that mosaic computes an infinite row, an infinite number of times. *However, reduction-completeness of DF* precludes infinite runaway.* Vectors are displayed as they are generated. The above program is compiled into:

reduce(rotate(A,B),[]) :- reduce(A,[]).
reduce(rotate(A,B),[v(C,D)--v(E,F)|rotate(G,B)]) :-
        reduce(A,[H|G]), reduce(H,I--J), reduce(I,v(K,L)),
        reduce(J,v(M,N)), cos(B,O), P is K*O, sin(B,Q),
        R is L*Q, C is P-R, sin(B,S), T is K*S,
        cos(B,U), V is L*U, D is T+V, cos(B,W),
        X is M*W, sin(B,Y), Z is N*Y, E is X-Z,
        sin(B,A1), B1 is M*A1, cos(B,C1), D1 is N*C1, F is B1+D1.
reduce(translate(A,B,C),[]):-reduce(A,[]).
reduce(translate(A,B,C),[v(D,E)--v(F,G)|translate(H,B,C)]) :-
        reduce(A,[I|H]), reduce(I,J--K), reduce(J,v(L,M)),
        reduce(K,v(N,O)), D is L+B, E is M+C,
        F is N+B, G is O+C.
reduce(scale(A,B,C),[]) :- reduce(A,[]).
reduce(scale(A,B,C),[v(D,E)--v(F,G)|scale(H,B,C)]) :-
        reduce(A,[I|H]), reduce(I,J--K), reduce(J,v(L,M)),
        reduce(K,v(N,O)), D is L*B, E is M*C, F is N*B, G is O*C.

reduce(true,true).
reduce(false,false).
reduce([],[]).
reduce([A|B],[A|B]).

reduce(A--B,A--B).
reduce(v(A,B),v(A,B)).

reduce(p,A) :- p=>B, reduce(B,A).
reduce(q,A) :- q=>B, reduce(B,A).
reduce(r,A) :- r=>B, reduce(B,A).
reduce(s,A) :- s=>B, reduce(B,A).
reduce(t,A) :- t=>B, reduce(B,A).
reduce(block1(A),B) :- block1(A)=>C, reduce(C,B).
reduce(block2(A),B) :- block2(A)=>C, reduce(C,B).
reduce(cycle(A),B) :- cycle(A)=>C, reduce(C,B).
reduce(rot(A),B) :- rot(A)=>C, reduce(C,B).
reduce(rot_neg(A),B) :- rot_neg(A)=>C, reduce(C,B).
reduce(rot_pos(A),B) :- rot_pos(A)=>C, reduce(C,B).
reduce(above1(A,B),C) :- above1(A,B)=>D, reduce(D,C).
reduce(alt_rows(A,B),C) :- alt_rows(A,B)=>D, reduce(D,C).
reduce(beside1(A,B),C) :- beside1(A,B)=>D, reduce(D,C).
reduce(mosaic(A,B),C) :- mosaic(A,B)=>D, reduce(D,C).
reduce(row(A,B),C) :- row(A,B)=>D, reduce(D,C).
reduce(union(A,B),C) :- reduce(A,D), union(D,B)=>E, reduce(E,C).
reduce(quartet(A,B,C,D),E) :- quartet(A,B,C,D)=>F, reduce(F,E).

union([],A)=>A.
union([A|B],C)=>[A|union(C,B)].
rot_pos(A)=>translate(rotate(translate(A,-72,-72),-1.57),72,0).
rot_neg(A)=>translate(rotate(translate(A,-72,-72),1.57),0,72).
block1(A)=>union(A,translate(rot_neg(A),72,0)).
block2(A)=>union(rot_pos(A),
        translate(rotate(translate(rot_pos(A),-72,0),-1.57),72,0)).
row(A,B)=>union(translate(A,C,0),
                union(translate(A,D,0),row(A,E))) :-
                        C is 144*B, D is-144*B, E is B+1.

```
alt_rows(A,B)=>union(translate(A,0,C),union(translate(A,0,D),alt_rows(A,E))):-
          C is 144*B, D is-144*B, E is B+1.
mosaic(A,B)=>union(alt_rows(row(A,0),0),
                translate(alt_rows(row(B,0),0),0,72)).
beside(A,B)=>union(A,translate(B,36,0)).
above(A,B)=>union(A,translate(B,0,36)).
quartet(A,B,C,D)=>above(beside(C,D),beside(A,B)).
rot(A)=>rotate(A,1.57).
cycle(A)=>union(A,union(rot(A),union(rot(rot(A)),rot(rot(rot(A)))))).
t=>quartet(p,q,r,s).
p=>[..].
q=>[..].
r=>[..].
s=>[..].
```

VI.8 FIRST TWO ELEMENTS OF A LIST

Tamaki [1984] shows how to compile restricted equality theories, expressed by a reducibility predicate =>, into Horn clauses with a small search space. For example, the clauses:

```
int(N)=>[Nlint(N+1)].
first2([X,YlZ],[X,Y]).
```

are compiled into:

```
X=>X
int(N)=>[NlZ]:-int(N+1)=>Z
first2([X,YlZ],[X,Y])
```

Now the query int(1)=>X,first2(X,Y) succeeds with answer substitution X=[1,2lint(3)], Y=[1,2]. However, it succeeds with infinitely many other distinct answer substitutions, e.g. X=[1,2,3lint(4)],Y=[1,2], X=[1,2,3,4lint(5)],Y=[1,2].... In LOG(F), however, we would first define:

```
int(N)=>[Nlint(N+1)]
first2([UlV])=>g(U,V)
g(U,[AlB])=>[U,A]
```

These would be compiled to:

```
reduce([],[]).
reduce([U|V],[U|V]).
reduce(int(N),Z):-N1 is N+1,reduce([N|int(N1)],Z).
reduce(first2(X),Z):-reduce(X,[U|V]), reduce(g(U,V),Z).
reduce(g(C,X),Z):-reduce(X,[A|B]),reduce([C,A],Z).
```

Now the query reduce(first2(int(1)),Z), would succeed with exactly one answer substitution, Z=[1,2]. This is as desired.

VI.9 COMPARING LOG(F) PERFORMANCE WITH THAT OF PROLOG

Programs of similar length, and intellectual complexity are written in both F* and in Prolog. The former were compiled into Prolog, and optimized, before being compared with the latter. The performance figures in Quintus Prolog on a SUN 3/50 are listed in the table below.

For problems in which data structures are always completely evaluated, lazy evaluation cannot reduce lengths of computation. Such problems include list reversal, or sorting. For these, LOG(F) is, on an average, five times slower than Prolog. However, the slowdown for a given problem appears to stay the same, regardless of the size of the input.

For problems in which data structures need only be partially evaluated, e.g. the N-queens problem, or tiling an infinite plane, lazy evaluation can reduce lengths of computation. For these, LOG(F) can be faster than Prolog by factors which are unbounded, i.e. grow with input size, and by factors which are infinite.

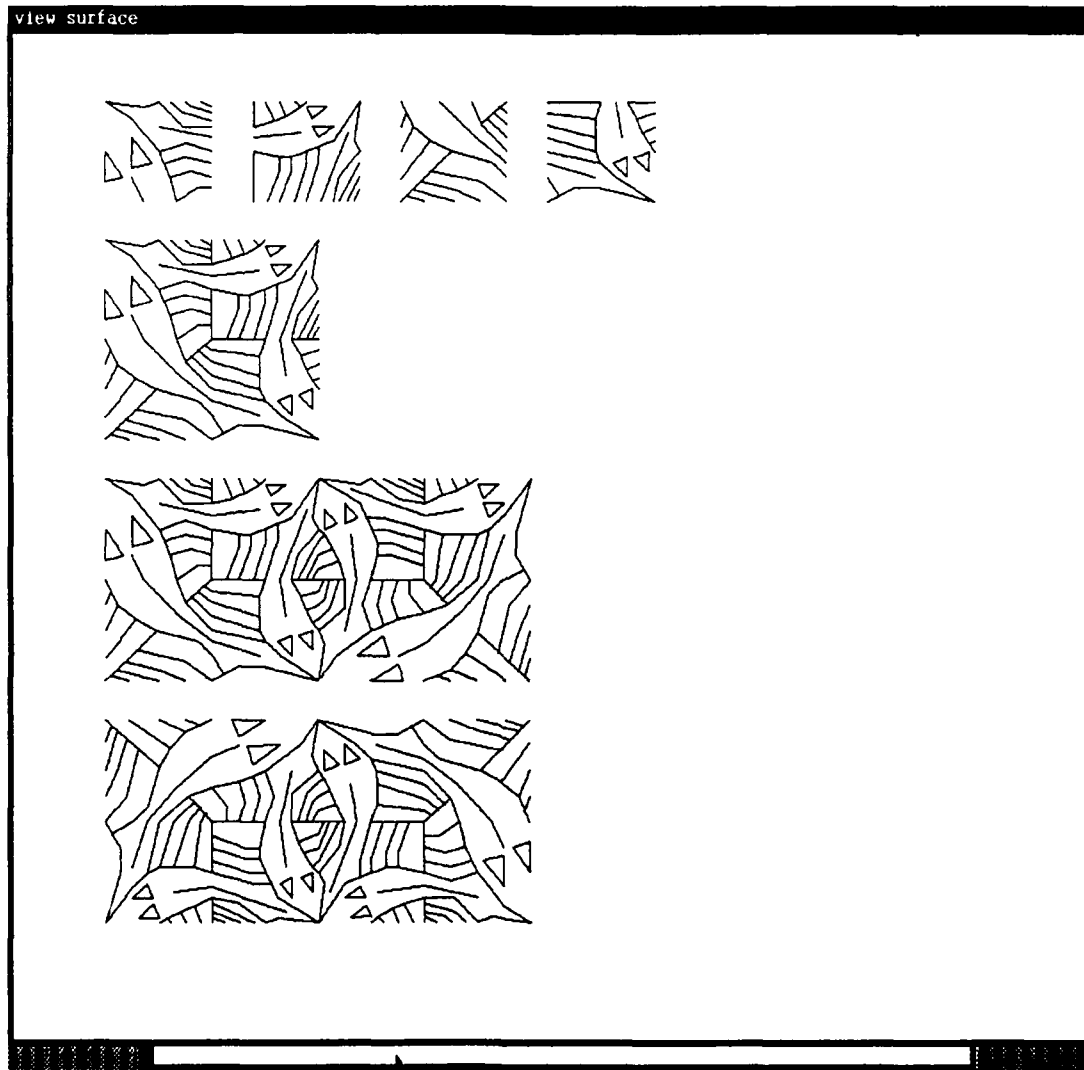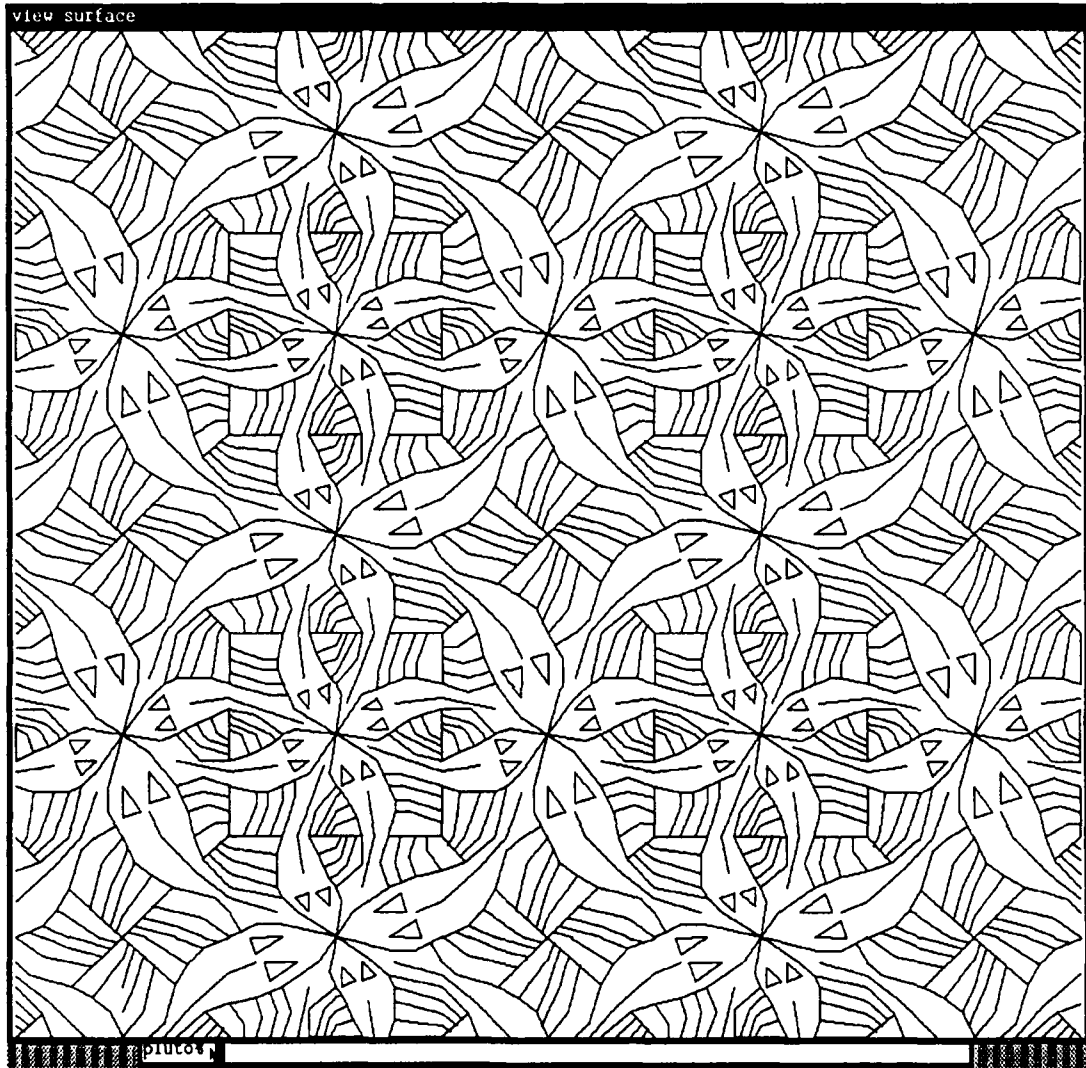| Time in milliseconds			
	Prolog	LOG(F)	Prolog/LOG(F)
Reverse: 3200 elements	83	883	0.09
Reverse: 6400 elements	150	1755	0.08
Quicksort: 60 elements	83	539	0.15
Quicksort: 120 elements	250	1261	0.19
Sieve: First 50 primes	422	1261	0.33
Sieve: First 100 primes	1816	4511	0.40
All permutations of [1,2,3,4,5]	427	516	0.82
All permutations of [1,2,3,4,5,6]	3000	3172	0.94
8-Queens: All solutions	62783	17511	3.58
9-Queens: All solutions	635144	86539	7.33
15-Queens: First solution	>30 minutes	30300	>60
Infinite plane: First vector	∞	~ 0	∞

Figure 1. Some Graphical Primitives

Figure 2. Square Unlimit

VII. SUMMARY AND CONCLUSIONS

A new approach for combining logic programming, rewriting, and lazy evaluation is described. It rests upon *subsuming* within logic programming, instead of upon *extending* it with, rewriting, and lazy evaluation.

F* is a non-terminating, non-deterministic rewrite rule system. The reduction strategy for it, select, is reduction-complete. DF* is a subset of F*, and is also non-terminating. DF* satisfies confluence, directedness, and minimality. Reduction-completeness, and minimality enable select to exhibit, respectively, weak and strong forms of laziness.

F* can be compiled into Horn clauses in such a way that when SLD-resolution interprets them, it directly simulates the behavior of select. In particular, it is made to exhibit laziness. LOG(F) is defined to be a logic programming system augmented with an F* compiler, and the equality axiom X=X. Since clauses obtained by compiling F* programs can be called from other logic programs, LOG(F) is proposed as a combination of logic programming, rewriting, and lazy evaluation.

LOG(F) offers, perhaps for the first time, an efficient implementation of lazy evaluation within a widely used language, namely, Prolog. For problems in which lazy evaluation cannot reduce lengths of computation, LOG(F) is somewhat slower than Prolog. For problems in which lazy evaluation does reduce lengths of computation, LOG(F) can be faster than Prolog by factors which are unbounded, i.e. grow with input size, and factors which are infinite.

LOG(F) can also be used to implement useful cases of the rule of substitution of equals for equals. Confluence of DF* yields a new proof of the confluence of combinatory logic. Finally, DF* seems to be a good candidate for implementation on parallel machines. It seems to offer a reasonable compromise between sequential execution and unbounded parallelism. Due to directedness of DF*, arguments of f in $f(t1,...,tm)$ can be simplified in parallel, however, they would be simplified lazily.

VIII. ACKNOWLEDGEMENTS

I am very grateful to my advisor, Professor D.S. Parker, for his guidance, encouragement, and criticism throughout the development of the thesis on which this paper is based. I also thank Professors Y.N. Moschovakis, David Jefferson, and Milos Ercegovac, and Dr. Hassan Ait-Kaci for their many valuable suggestions.

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